# A geometrical proof of Shiota's theorem on a conjecture of S. P. Novikov 

GIAMBATTISTA MARINI<br>Dipartimento di Matematica, II Università degli Studi di Roma 'Tor Vergata', Via della Ricerca Scientifica - 00133 Roma, Italy; e-mail: marini@axp.mat.utovrm.it

Received 1 March 1995; accepted in final form 6 February 1997


#### Abstract

We give a new proof of Shiota's theorem on Novikov's conjecture, which states that the K.P. equation characterizes Jacobians among all indecomposable principally polarized abelian varieties.


Mathematics Subject Classifications (1991): 14K25, 14H40.
Key words: characterization of Jacobians, K.P. equation, K.P. hierarchy.
The Kummer variety of a Jacobian has a 4-parameter family of trisecants. Using Riemann's relations, Fay's identity and limit considerations, this property has been translated in a hierarchy of non-linear partial differential equations which is satisfied by the theta function of a Jacobian (see [F], [Mu], [Du], [Kr], [AD3]).

Novikov's conjecture stated that if a theta function associated with an indecomposable principally polarized abelian variety $(X,[\Theta])$ satisfies the K.P. equation, the first equation of the hierarchy, then $(X,[\Theta])$ is the Jacobian of a complete irreducible smooth curve. Shiota originally proved the conjecture in [ S ] by the use of hard techniques from the theory of non-linear partial differential equations. His proof was later simplified by Arbarello and De Concini (see [AD2]). We give a proof of the theorem which is more geometrical in character; in particular we avoid a technical point, namely Shiota's Lemma 7, which is instrumental in both Shiota's and Arbarello-De Concini's proofs. For our proof, we follow Arbarello and De Concini algebro-geometrical attempt to solve the problem (see [A] and [AD3]) and we go further. First, let us recall that in order to prove Novikov's conjecture, it suffices to recover the whole K.P. hierarchy from its first equation (because of Welters' version of Gunning's criterion). The key point in Arbarello and De Concini geometrical approach is that, no matter what are the parameters in the equations in the K.P. hierarchy, it turns out that the terms to be equated to zero form a sequence of sections of the line bundle $\mathcal{O}(2 \Theta)$. One needs to find parameters that make this sequence into the identically zero sequence. The difficulty comes from the fact that the theta divisor may have, a priori, a difficult geometry. The key object in the approach in [A] and [AD3] is the subscheme $D_{1} \Theta$ of $\Theta$ defined by the zeroes of the section of $\mathcal{O}_{\Theta}(\Theta)$ associated with $D_{1} \theta$, where $D_{1}$ is an invariant vector field that appears in the expression of the first equation of the hierarchy, and $\theta$ is the
theta function associated with $\mathcal{O}_{X}(\Theta)$. As it was pointed out in [A] and [AD3], the reduced components of $D_{1} \Theta$ do not create much trouble. They provide a geometrical proof of the conjecture under the additional hypotheses that the singular locus of the theta divisor has codimension at least 2 , and that the scheme $D_{1} \Theta$ does not contain components which are invariant under the $D_{1}$-flow. We remove Arbarello-De Concini's additional hypotheses by proving the following. If the K.P. equation holds, the components of codimension one of the singular locus of the theta divisor are invariant under the $D_{1}$-flow (for this we make use of a result of Kollár about the singularities of the theta divisor). Therefore every component of $D_{1} \Theta$ which creates trouble is $D_{1}$-invariant and, in particular, it contains a translate of an abelian subvariety of $X$. We then prove that the theta function of an abelian variety which contain an abelian subvariety as above, is not a solution of the K.P. equation. For this we combine an algebraic computation which was discovered by Shiota (namely his Lemmas A and B, which we restate and reprove for the convenience of the reader), and a technical lemma on the obstructions to recover the K.P. hierarchy (Lemma 3.11).

For the discrete analogue to Novikov's conjecture see [De]. For further discussions see [AD3], [Do], [GG], [Ma].

## 1. Introduction

Let $C$ be a smooth complex curve, $J(C)$ its Jacobian, $\operatorname{Pic}^{d}(C)$ the Picard group of line bundles of degree $d$ on $C$ and $\Gamma$ the image of $C$ via the Abel-Jacobi embedding associated with an element of $\mathrm{Pic}^{-1}(C)$.

Let $(X,[\Theta])$ be an i.p.p.a.v. (indecomposable, principally polarized, abelian variety) of dimension $n$, and let $\Theta$ be a symmetric representative of the polarization. We shall denote by $\theta$ a theta function associated with $\mathcal{O}_{X}(\Theta)$; in particular, $\theta$ is naturally a nonzero section of $\mathcal{O}_{X}(\Theta)$.

The image of the morphism

$$
K: X \rightarrow|2 \Theta|^{*}
$$

associated with the base-point-free linear system $|2 \Theta|$ is a projective variety which is called the Kummer variety of $(X,[\Theta])$.

The Kummer variety of $J(C)$ has a rich geometry in terms of trisecants and flexes which is a consequence of the equality

$$
W_{g-1}^{0} \cap\left(W_{g-1}^{0}+p-q\right)=\left(W_{g}^{1}-q\right) \cup\left(W_{g-2}^{0}+p\right) \quad \forall p, q \in C, \quad p \neq q
$$

where $W_{d}^{r}=\left\{|D| \in \operatorname{Pic}^{d}(C)|\operatorname{dim}| D \mid \geqslant r\right\}$. Indeed, the inclusion

$$
\Theta_{\beta} \cap \Theta_{\gamma} \subset \Theta_{\alpha} \cup \Theta_{\beta+\gamma-\delta}, \quad \forall \alpha, \beta, \gamma, \delta \in \Gamma, \quad \beta \neq \gamma
$$

(where $\Theta_{p}:=\Theta+p$ ), the linear dependence of the sections

$$
\theta(z-\alpha) \cdot \theta(z-\beta-\gamma+\delta), \quad \theta(z-\beta) \cdot \theta(z-\alpha-\gamma+\delta),
$$

$$
\theta(z-\gamma) \cdot \theta(z-\alpha-\beta+\delta)
$$

and the collinearity in the projective space $|2 \Theta|^{*}$ of the points

$$
\begin{aligned}
& K(\xi+\alpha), \quad K(\xi+\beta) \\
& K(\xi+\gamma), \quad \forall \alpha, \beta, \gamma, \delta \in \Gamma, \quad \forall \xi \in \frac{1}{2}(\delta-\alpha-\beta-\gamma)
\end{aligned}
$$

are all different translations (via Abel and Riemann's theorems) of the previous equality. In particular, once distinct points $\alpha, \beta, \gamma$ are fixed, one has a family of trisecants parametrized by $\frac{1}{2} \Gamma$. Considering the limit situation where $\beta$ and $\gamma$ tend to $\alpha$ one obtain a family of flexes parametrized by $\frac{1}{2} \Gamma$.

This property has been used to characterize Jacobians among all principally polarized abelian varieties (see [G], [W]). Welters' improvement of Gunning's theorem states that an i.p.p.a.v. $(X, \Theta)$ is a Jacobian if and only if there exists an Artinian subscheme $Y$ of $X$ of length 3, such that the algebraic subset $V=$ $\left\{2 \xi \mid \xi+Y \subset K^{-1}(l)\right.$ for some line $\left.l \subset|2 \Theta|^{*}\right\}$ has positive dimension at some point (if this is the case it turns out that $V$ is isomorphic to the curve $C$ ). In particular one has:

PROPOSITION $1.1[\mathrm{AD} 1]$. Let $(X,[\Theta])$ be an i.p.p.a.v.. The following statements are equivalent:
(a) the i.p.p.a.v. $(X,[\Theta])$ is isomorphic to the Jacobian of a curve;
(b) there exist invariant vector fields $D_{1} \neq 0, D_{2}, \ldots$, on $X$ such that

$$
\operatorname{dim}\left\{\xi \in X \mid K(\xi) \wedge D_{1} K(\xi) \wedge\left(D_{1}^{2}+D_{2}\right) K(\xi)=0\right\} \geqslant 1 ;
$$

(b') there exist invariant vector fields $D_{1} \neq 0, D_{2}, \ldots$, on $X$ and constants $d_{4}, d_{5}, \ldots$, such that

$$
\begin{aligned}
P_{m} \theta(z):= & {\left[\Delta_{m} D_{1}-\Delta_{m-1}\left(D_{2}+D_{1}^{2}\right)+\sum_{i=3}^{m} d_{i+1} \Delta_{m-i}\right][\theta(z+\zeta)} \\
& \cdot \theta(z-\zeta)]\left.\right|_{\zeta=0}=0
\end{aligned}
$$

for all $m \geqslant 3$, where the $D_{i}$ operate on the variable $\zeta$, and the $\Delta_{j}$ are defined by

$$
\Delta_{j}=\sum_{i_{1}+2 i_{2}+\cdots+j i_{j}=j} \frac{1}{i_{1}!\cdot i_{2}!\cdot \cdots \cdot i_{j}!} \cdot D_{1}^{i_{1}} \cdots D_{j}^{i_{j}} .
$$

In this case, the image curve $\Gamma$ is, up to translation, the curve whose parametric expression is

$$
\varepsilon \mapsto \sum_{i=1}^{\infty} \varepsilon^{i} \cdot 2 D_{i}
$$

where $\varepsilon \in \mathbb{C}$, and each $D_{i}$ is viewed as a point of the universal cover of $X$ via its natural identification with $T_{0}(X)$.

## 2. Shiota's theorem

First, we observe that

$$
\begin{align*}
P_{3}\left(D_{1}, D_{2}, D_{3} ; d\right) \theta= & {\left.\left[-\frac{1}{3} D_{1}^{4}-D_{2}^{2}+D_{1} D_{3}+d\right][\theta(z+\zeta) \cdot \theta(z-\zeta)]\right|_{\zeta=0} } \\
= & -\frac{2}{3} D_{1}^{4} \theta \cdot \theta+\frac{8}{3} D_{1}^{3} \theta \cdot D_{1} \theta-2 D_{1}^{2} \theta \cdot D_{1}^{2} \theta \\
& +2 D_{2} \theta \cdot D_{2} \theta-2 D_{2}^{2} \theta \cdot \theta \\
& +2 D_{1} D_{3} \theta \cdot \theta-2 D_{3} \theta \cdot D_{1} \theta+d \theta \cdot \theta \tag{2.0}
\end{align*}
$$

THEOREM 2.1 (Shiota [ S ], conjectured by Novikov). The first non-trivial equation of the K.P. hierarchy characterizes Jacobians: an i.p.p.a.v. $(X,[\Theta])$ is a Jacobian if and only if there exist invariant vector fields $D_{1} \neq 0, D_{2}, D_{3}$ and a constant d such that

$$
P_{3}\left(D_{1}, D_{2}, D_{3} ; d\right) \theta=0
$$

As we already mentioned, our proof consists in recovering the vanishing of the whole K.P. hierarchy from the equation $P_{3} \theta=0$, i.e. in recovering the curve $\Gamma$ from its third order approximation. We observe that $P_{i}(\ldots) \theta$ is a section of $\mathcal{O}_{X}(2 \Theta)$, for all $D_{1}, \ldots, D_{i}$ and $d_{4}, \ldots, d_{i+1}$. Indeed, if $\mathcal{D}$ is any differential operator, because of Riemann's quadratic identity, we have that

$$
\left.\mathcal{D}[\theta(z+\zeta) \cdot \theta(z-\zeta)]\right|_{\zeta=0}=\sum_{\nu \in Z^{g} / 2 Z^{g}} \mathcal{D} \theta_{\nu}(0) \cdot \theta_{\nu}(z) \in H^{0}(X, 2 \Theta),
$$

where $\left\{\theta_{\nu}\right\}$ is the basis of $H^{0}(X, \mathcal{O}(2 \Theta))$ having the property that Riemann's identity $\theta(z+\zeta) \cdot \theta(z-\zeta)=\Sigma_{\nu} \theta_{\nu}(z) \cdot \theta_{\nu}(\zeta)$ holds. Assuming by induction that there exist invariant vector fields $D_{1}, \ldots, D_{m-1}$ and constants $d_{4}, \ldots, d_{m}$ such that

$$
P_{i}\left(D_{1}, \ldots, D_{i} ; d_{4}, \ldots, d_{i+1}\right) \theta=0, \quad \forall i \leqslant m-1,
$$

one needs to find $D_{m}$ and $d_{m+1}$ such that $P_{m}(\ldots) \theta=0$.
We recall that the vector space $H^{0}\left(\Theta,\left.\mathcal{O}(\Theta)\right|_{\Theta}\right)$ is the vector space of derivatives $T \theta$, with $T \in T_{0}(X)$. We denote by $D \Theta$ the scheme associated with the section $D \theta \in H^{0}\left(\Theta,\left.\mathcal{O}(\Theta)\right|_{\Theta}\right)$, i.e. $D \Theta=\Theta \cap\{D \theta=0\}$. We shall use the following remark.

REMARK 2.2 [AD3] (private communication from G. Welters to E. Arbarello). Whenever a section $S \in H^{0}(X, \mathcal{O}(2 \Theta))$ vanishes on $D \Theta$, there exists an invariant vector field $E$ and a constant $d$ such that

$$
S+E D \theta \cdot \theta-E \theta \cdot D \theta+d \theta \cdot \theta=0 \in H^{0}(X, \mathcal{O}(2 \Theta))
$$

As a consequence of this remark, Shiota's theorem can be stated as follows.
THEOREM 2.3. An i.p.p.a.v. $(X,[\Theta])$ is a Jacobian if and only if there exist invariant vector fields $D_{1} \neq 0$ and $D_{2}$ such that $\left.P_{3}\left(D_{1}, D_{2}, 0 ; 0\right) \theta\right|_{D_{1} \Theta}=0$.

REMARK 2.4. We work with the K.P. differential equation for a theta function, which is an automorphic form $\theta$ associated with the polarization. If $\theta(z)$ and $\tilde{\theta}(z)$ are automorphic forms associated with the same polarization, there exists a point $z_{0}$ in $V$, where $V$ is the universal cover of the abelian variety $X$, and a nowherevanishing holomorphic function $g(z)$ on $V$, such that $\tilde{\theta}\left(z+z_{0}\right)=g(z) \cdot \theta(z)$. One might have $P_{3} \theta=0$ and $P_{3} \tilde{\theta} \neq 0$ but, since $P_{3}(g \cdot \theta)=g^{2} \cdot P_{3} \theta+\theta^{2} \cdot P_{3} g-d \cdot g^{2}$. $\theta^{2}-8\left(D_{1}^{2} g \cdot g-D_{1} g \cdot D_{1} g\right) \cdot\left(D_{1}^{2} \theta \cdot \theta-D_{1} \theta \cdot D_{1} \theta\right)$, one has $\left.P_{3} \tilde{\theta}\right|_{D_{1} \Theta}=\left.g^{2} \cdot P_{3} \theta\right|_{D_{1} \Theta}$ (so that formulation 2.3 of Shiota's theorem is independent of the theta function representing the polarization). In view of Remark 2.2, there exist $D_{1}, D_{2}, D_{3}, d$ such that $P_{3}\left(D_{1}, D_{2}, D_{3} ; d\right) \theta=0$ if and only if there exist $D_{1}, D_{2}, \tilde{D}_{3}, \tilde{d}$ such that $P_{3}\left(D_{1}, D_{2}, \tilde{D}_{3} ; \tilde{d}\right) \tilde{\theta}=0$.

TWO FORMULAS 2.5. We have the general formulas (they can be proved by a direct computation)

$$
\begin{aligned}
& \left(P_{s}+\sum_{i=1}^{s-3} \Delta_{i} P_{s-i}\right) \theta \\
& =\left(D_{1}^{2} \theta-D_{2} \theta\right) \cdot\left(-\tilde{\Delta}_{s-1} \theta\right) \\
& \quad+\theta \cdot\left[D_{1} \tilde{\Delta}_{s}-\left(D_{1}^{2}+D_{2}\right) \tilde{\Delta}_{s-1}+\sum_{i=3}^{s} d_{i+1} \tilde{\Delta}_{s-i}\right] \theta \\
& \quad+D_{1} \theta \cdot\left(-\tilde{\Delta}_{s}+2 D_{1} \tilde{\Delta}_{s-1}\right) \theta, \\
& \left(P_{s}+\sum_{i=1}^{s-3} \Delta_{i}^{-} P_{s-i}\right) \theta \\
& = \\
& \left(D_{1}^{2} \theta+D_{2} \theta\right) \cdot\left(-\tilde{\Delta}_{s-1}^{-} \theta\right) \\
& \quad+\theta \cdot\left[-D_{1} \tilde{\Delta}_{s}^{-}-\left(D_{1}^{2}-D_{2}\right) \tilde{\Delta}_{s-1}^{-}+\sum_{i=3}^{s} d_{i+1} \tilde{\Delta}_{s-i}^{-}\right] \theta \\
& \\
& \quad-D_{1} \theta \cdot\left(-\tilde{\Delta}_{s}^{-}-2 D_{1} \tilde{\Delta}_{s-1}^{-}\right) \theta,
\end{aligned}
$$

where $\Delta_{i}^{-}\left(D_{1}, \ldots, D_{i}\right)=\Delta_{i}\left(-D_{1}, \ldots,-D_{i}\right), \tilde{\Delta}_{i}\left(D_{1}, \ldots, D_{i}\right)=\Delta_{i}\left(2 D_{1}, \ldots\right.$, $\left.2 D_{i}\right), \tilde{\Delta}_{i}^{-}\left(D_{1}, \ldots, D_{i}\right)=\Delta_{i}\left(-2 D_{1}, \ldots,-2 D_{i}\right)$.

REMARK 2.6 [AD3]. The restriction $\left.P_{m} \theta\right|_{D_{1} \Theta}$ does not depend on $D_{m}, d_{m+1}$. In fact

$$
\begin{aligned}
& P_{m}\left(D_{1}, \ldots, D_{m} ; d_{4}, \ldots, d_{m+1}\right) \theta \\
& \quad=P_{m}\left(D_{1}, \ldots, D_{m-1}, 0 ; d_{4}, \ldots, d_{m}, 0\right) \theta+2 D_{m} D_{1} \theta \cdot \theta \\
& \quad-2 D_{m} \theta \cdot D_{1} \theta+d_{m+1} \theta^{2}
\end{aligned}
$$

This equality leads to a crucial point of Arbarello-De Concini's argument: by Remark 2.2, there exist a $D_{m}$ and a $d_{m+1}$ which make $P_{m} \theta$ equal to zero if and only if $P_{m} \theta$ vanishes on $D_{1} \Theta$.

From the formulas in 2.5 and the previous remark, assuming by induction that $P_{i} \theta=0$ for $i<m$, it follows that the only obstruction to find a $D_{m}$ and a $d_{m+1}$ which make $P_{m} \theta$ equal to zero is given by those components of $D_{1} \Theta$ where neither $\left(D_{1}^{2}+D_{2}\right) \theta$ nor $\left(D_{1}^{2}-D_{2}\right) \theta$ vanish. Since $P_{3} \theta$ equals $\left(D_{1}^{2}+D_{2}\right) \theta \cdot\left(D_{1}^{2}-D_{2}\right) \theta$, $\bmod \left(\theta, D_{1} \theta\right)$, and since, by hypothesis, $P_{3} \theta=0$, we have that $\left(D_{1}^{2}+D_{2}\right) \theta \cdot\left(D_{1}^{2}-\right.$ $\left.D_{2}\right) \theta$ vanishes on $D_{1} \Theta$. Therefore a component of $D_{1} \Theta$ where neither $\left(D_{1}^{2}+D_{2}\right) \theta$ nor $\left(D_{1}^{2}-D_{2}\right) \theta$ vanish must be non-reduced.

In the next section we shall deal with such components. We show that if $\mathcal{W}$ is a component of $D_{1} \Theta$ then, assuming by induction that $P_{3} \theta=\cdots=P_{m-1} \theta=0$, only two cases may occur: either $P_{m} \theta$ vanishes on $\mathcal{W}$, or the reduced scheme underlying $\mathcal{W}$, denoted by $\mathcal{W}_{\text {red }}$, is invariant under the $\left\langle D_{1}, D_{2}\right\rangle$-flow. Moreover, if $\Theta$ is singular along $\mathcal{W}_{\text {red }}$ then the second case occur (Theorems 3.1 and 3.2).

## 3. The $\left\langle D_{1}, D_{2}\right\rangle$-invariance

To begin, we observe that we can always assume $D_{2} \neq 0$, as well as $D_{3} \neq 0$. Indeed, for all complex numbers $b$, we have

$$
\begin{equation*}
P_{3}\left(D_{1}, D_{2}, D_{3} ; d_{4}\right)=P_{3}\left(D_{1}, D_{2}+b D_{1}, D_{3}+2 b D_{2}+b^{2} D_{1} ; d_{4}\right) \tag{3.0}
\end{equation*}
$$

Let $\mathcal{W}$ be a component of $D_{1} \Theta$. We assume first that $\Theta$ is smooth at a generic point of $\mathcal{W}_{\text {red }}$. We prove the following.

THEOREM 3.1. Let $(X,[\Theta])$ be an i.p.p.a.v. of dimension $n$ and assume that $P_{3} \theta=\cdots=P_{m-1} \theta=0$, where $m \geqslant 4$. Let $\mathcal{W}$ be a component of the scheme $D_{1} \Theta$ and assume that $\Theta$ is non-singular at a generic point of $\mathcal{W}_{\text {red }}$. Then either $P_{m} \theta$ vanishes on $\mathcal{W}$, or $\mathcal{W}_{\text {red }}$ is invariant under the $\left\langle D_{1}, D_{2}\right\rangle$-flow.

Proof. Let $p$ be a generic point of $\mathcal{W}_{\text {red }}$. If $\mathcal{W}$ is reduced, $P_{m} \theta$ vanishes on $\mathcal{W}$. Assume that $\mathcal{W}$ is non-reduced. Since $p$ is a smooth point of $\Theta$, there exist an
irreducible element $h \in \mathcal{O}_{X, p}$, an integer $a \geqslant 2$, integers $b, c$, invertible elements $\varepsilon_{2}, \varepsilon_{3} \in \mathcal{O}_{X, p}$ and elements $g_{1}, g_{2}, g_{3} \in \mathcal{O}_{X, p}$ such that the ideal of $\mathcal{W}$ in $\mathcal{O}_{X, p}$ is of the form ( $h^{a}, \theta$ ), and moreover

$$
\begin{align*}
& D_{1} \theta=h^{a}+g_{1} \cdot \theta \\
& D_{2} \theta=\varepsilon_{2} \cdot h^{b}+g_{2} \cdot \theta  \tag{3.1.1}\\
& D_{3} \theta=\varepsilon_{3} \cdot h^{c}+g_{3} \cdot \theta \\
& D_{1}^{2} \theta=a \cdot h^{a-1} \cdot D_{1} h+g_{1} \cdot h^{a}+\left[g_{1}^{2}+D_{1} g_{1}\right] \cdot \theta
\end{align*}
$$

We have $b \geqslant 1$, because $P_{3} \theta$, hence $\left(D_{1}^{2} \theta+D_{2} \theta\right) \cdot\left(D_{1}^{2} \theta-D_{2} \theta\right)$, vanishes on $\mathcal{W}_{\text {red }}$. If $h$ does not divide $D_{1} h$, we prove as in [A] that $P_{m} \theta$ vanishes on $\mathcal{W}$ : by substituting the formulas above in the expression of $P_{3} \theta$ and $D_{1} P_{3} \theta$, one sees that $a$ has to equal 2 and by substituting in the expression of $P_{m-1} \theta$ (which is zero by inductive hypothesis), one sees that $\Delta_{m-1} \theta$ belongs to $(h, \theta)$; hence $P_{m} \theta \in\left(h^{2}, \theta\right)$, that is $\left.P_{m} \theta\right|_{\mathcal{W}}=0$.

If $h$ divides $D_{1} h$, the variety $\mathcal{W}_{\text {red }}$ is invariant under the $D_{1}$-flow. Under this assumption, the $\left\langle D_{1}, D_{2}\right\rangle$-invariance of $\mathcal{W}_{\text {red }}$ is a consequence of Lemma 3.5 and Lemma 3.8 below.

Let us now turn to the case

$$
\operatorname{dim} \Theta_{\text {sing }}=n-2, \quad \Theta \text { is singular along } \mathcal{W}_{\text {red }} .
$$

(During the revision of the manuscript the preprint by Ein and Lazrsfeld [EL] appeared proving that the case $\Theta_{\text {sing }}=n-2$ does not actually occur. Therefore, Theorem 3.2, Lemma 3.6 and Lemma 3.7 below are no longer strictly necessary for the present proof). We want to prove the following.

THEOREM 3.2. Let $(X,[\Theta])$ be an i.p.p.a.v. of dimension n. Suppose the divisor $\Theta$ is singular along a reduced subvariety $Z$ of codimension 1, and assume that the K.P. equation $P_{3} \theta=0$ holds. Then $Z$ is invariant under the $\left\langle D_{1}, D_{2}\right\rangle$-flow.

This theorem is consequence of Lemma 3.5, Lemma 3.7 and Lemma 3.8 below; it will be proved later.

REMARK 3.3. We will make a strong use of the fact that $Z$ has codimension 2 in $X$. It is clearly in general false that, if the K.P. equation holds, $\Theta$ is $D_{1}$-invariant in its singular points.

In view of the following general fact proved by J. Kollár in [Ko] the theta divisor cannot be 'too singular' along $Z$.

THEOREM 3.4 (Kollár). Let $(X,[\Theta])$ be an i.p.p.a.v. . If $\Theta$ is singular along an
irreducible hypersurface $Z$, it has a local normal crossing singularity at a generic point of $Z$.

LEMMA 3.5. Let $(X,[\Theta])$ be an i.p.p.a.v. of dimension $n$, let $Z$ be a reduced subvariety of $\Theta$ of dimension $n-2$, and let $D$ be an invariant vector field on $X$. If $\Theta$ is $D$-invariant along $Z$, then $Z$ is $D$-invariant.

Proof. If $Z$ were not $D$-invariant, the $D$-span of $Z$ would be contained in $\Theta$. This span would have dimension $n-1$, therefore it would be a $D$-invariant component of $\Theta$. This is impossible because of the ampleness and the irreducibility of $\Theta$.

LEMMA 3.6. Suppose the divisor $\Theta$ is singular along $Z$, and assume that the K.P. equation $P_{3} \theta=0$ holds. Let $p$ be a smooth point of $Z$ and $T_{p}(Z)$ the tangent space to $Z$ at $p$. Then $D_{1}, D_{2}, T_{p}(Z)$ are not in general position, i.e.

$$
\operatorname{dim}\left(\left\langle D_{1}, D_{2}, T_{p}(Z)\right\rangle\right) \leqslant n-1
$$

Proof. Since $\Theta$ is singular along $Z$, we have that $\left.\theta\right|_{Z}=\left.D_{1} \theta\right|_{Z}=\left.D_{2} \theta\right|_{Z}=$ $\left.D_{3} \theta\right|_{Z}=0$. It follows that $\left.P_{3} \theta\right|_{Z}=\left.\left(D_{1}^{2} \theta\right)^{2}\right|_{Z}$, therefore $\left.D_{1}^{2} \theta\right|_{Z}=0$. By 2.0 we get $\left.D_{2} P_{3} \theta\right|_{Z}=\left.\left[\frac{8}{3} D_{1} D_{2} \theta \cdot D_{1}^{3} \theta\right]\right|_{Z}$ and $\left.D_{1}^{2} P_{3} \theta\right|_{Z}=\left.\left[\frac{-4}{3}\left(D_{1}^{3} \theta\right)^{2}+4\left(D_{1} D_{2} \theta\right)^{2}\right]\right|_{Z}$. Since $P_{3} \theta$ is zero, $D_{2} P_{3} \theta$ and $D_{1}^{2} P_{3} \theta$ are also zero, and therefore we obtain

$$
\begin{equation*}
\left.D_{1} D_{2} \theta\right|_{Z}=\left.D_{1}^{3} \theta\right|_{Z}=0 \tag{3.6.1}
\end{equation*}
$$

We now proceed by contradiction. Suppose there exists $p_{0} \in Z_{\text {smooth }}$ such that

$$
\left\langle D_{1}, D_{2}, T_{p_{0}}(Z)\right\rangle=T_{p_{0}}(X),
$$

then the same equality must hold for every $p$ in a neighborhood $U$ of $p_{0}$ in $Z$. Let $p \in U$. For every $E \in T_{p}(X)$, there exist $\lambda, \mu$ such that $E=S+\lambda D_{1}+\mu D_{2}$, where $S \in T_{p}(Z)$. As $\left.D_{1} \theta\right|_{Z}=0$ and $S \in T_{p}(Z)$ we have $E D_{1} \theta(p)=$ $\left(S+\lambda D_{1}+\mu D_{2}\right) D_{1} \theta(p)=0$. Therefore $\left.E D_{1} \theta\right|_{Z}=0$, for every $E \in T_{0}(X)$. The assumption that $\left\langle D_{1}, D_{2}, T_{p}(Z)\right\rangle=T_{p}(X)$ implies that $D_{1} \notin T_{p}(Z)$. By Theorem 3.4, the tangent cone to $\Theta$ at $p$ is a pair of distinct hyperplanes whose intersection is $T_{p}(Z)$. Therefore, for a generic $E \in T_{p}(X)$, we have that $\left.E D_{1} \theta\right|_{Z} \neq 0$. This is a contradiction.

LEMMA 3.7. Suppose the divisor $\Theta$ is singular along $Z$, and assume that the K.P. equation $P_{3} \theta=0$ holds. The divisor $\Theta$ is $D_{1}$-invariant at each point of $Z$.

Proof. From the previous lemma, there exist functions $\lambda$ and $\mu$ on $Z_{\text {smooth }}$ not simultaneously vanishing and such that

$$
\lambda(p) \cdot D_{1}+\mu(p) \cdot D_{2} \in T_{p}(Z)
$$

for all $p$ in $Z_{\text {smooth }}$. If $\mu \equiv 0$ then $Z$ is $D_{1}$-invariant. Assume $\mu \not \equiv 0$; by induction on $\alpha+\beta$, we prove that $\left.D_{1}^{\alpha} D_{2}^{\beta} \theta\right|_{Z}=0$, for all integers $\alpha, \beta$. Let us assume that $\left.D_{1}^{\alpha} D_{2}^{\beta} \theta\right|_{Z}=0$, for all $\alpha+\beta \leqslant \nu_{0}$. We need only to show that $D_{1}^{\nu_{0}+1} \theta$ vanishes on $Z$. In fact, since $\lambda(p) \cdot D_{1}+\mu(p) \cdot D_{2}$ is in $T_{p}(Z)$, and since $\mu$ is not identically zero, the vector $D_{2}$ is a combination of $D_{1}$ and a vector in $T_{p}(Z)$, for $p$ generic in $Z$; as $D_{1}^{\alpha} \theta$ vanishes on $Z$ for all $\alpha \leqslant \nu_{0}+1$, we have that $\left.D_{1}^{\alpha} D_{2}^{\beta} \theta\right|_{Z}=0$, for all $\alpha+\beta \leqslant \nu_{0}+1$. By 3.6.1, $\left.D_{1}^{3} \theta\right|_{Z}=0$; hence we are done if $\nu_{0} \leqslant 2$. Assume $\nu_{0} \geqslant 3$. We distinguish two cases:
(a) $D_{3} \in\left\langle D_{1}, D_{2}, T_{p}(Z)\right\rangle$, for all $p$ in $Z$;
(b) $D_{3} \notin\left\langle D_{1}, D_{2}, T_{p}(Z)\right\rangle$, for $p$ generic in $Z$.

Let us start with (a). Since $D_{3}$ is a combination of $D_{1}, D_{2}$ and a vector in $T_{p}(Z)$, it follows that $\left.D_{1}^{\alpha} D_{2}^{\beta} D_{3}^{\gamma} \theta\right|_{Z}=0$, for $\alpha+\beta+\gamma \leqslant \nu_{0}$. Therefore, the only nonzero terms in the restriction to $Z$ of a derivative of $P_{3} \theta$ are products of derivatives of $\theta$ of order at least $\nu_{0}+1$; as $P_{3} \theta=-\frac{2}{3} D_{1}^{4} \theta \cdot \theta+\frac{8}{3} D_{1}^{3} \theta \cdot D_{1} \theta-2 D_{1}^{2} \theta \cdot D_{1}^{2} \theta+$ 'lower order terms' we obtain that the only nonzero term of $\left.D_{1}^{2 \nu_{0}-2} P_{3} \theta\right|_{Z}$ is $D_{1}^{\nu_{0}+1} \theta \cdot D_{1}^{\nu_{0}+1} \theta$, with coefficient $-2\binom{2 \nu_{0}-2}{\nu_{0}-1}+\frac{8}{3}\binom{2 \nu_{0}-2}{\nu_{0}-2}-\frac{2}{3}\binom{\left(\nu_{0}-2\right.}{\nu_{0}-3}$ (which is easily seen to be nonzero). Therefore, as $\left.D_{1}^{2 \nu_{0}-2} P_{3} \theta\right|_{Z}=0$, we must have $\left.D_{1}^{\nu_{0}+1} \theta\right|_{Z}=0$.

Let us deal with case (b). Since $\left.D_{1}^{\alpha} D_{2}^{\beta} \theta\right|_{Z}=0$ for all $\alpha+\beta \leqslant 3 \leqslant \nu_{0}$, we have

$$
\begin{aligned}
& 0=\left.D_{1}^{4} P_{3} \theta\right|_{Z}=\left.\left(-2 D_{1}^{4} \theta \cdot D_{1}^{4} \theta-6 D_{1}^{4} \theta \cdot D_{1} D_{3} \theta\right)\right|_{Z} \\
& 0=\left.D_{1} D_{3} P_{3} \theta\right|_{Z}=\left.\left(2 D_{1}^{4} \theta \cdot D_{1} D_{3} \theta\right)\right|_{Z}
\end{aligned}
$$

It follows that $\left.D_{1}^{4} \theta\right|_{Z}=0$, and we may assume $\nu_{0} \geqslant 4$. We want to compute $\left.D_{1}^{\nu_{0}+1} P_{3} \theta\right|_{Z}$. Since any term of $P_{3} \theta$ is a product of derivatives of $\theta$ of order $i$ and $j$, where $i+j \leqslant 4$, any term of $\left.D_{1}^{\nu_{0}+1} P_{3} \theta\right|_{Z}$ is a product of derivatives of $\theta$ of order $i$ and $j$, where $i+j \leqslant \nu_{0}+5<2 \nu_{0}+2$. Thus, since $\left.D_{1}^{\alpha} D_{2}^{\beta} \theta\right|_{Z}=0$ for all $\alpha+\beta \leqslant \nu_{0}$, any contribution to the restriction to $Z$ of $D_{1}^{\nu_{0}+1} P_{3} \theta$ must involve a $D_{3}$; therefore, by $2.0,\left.D_{1}^{\nu_{0}+1} P_{3} \theta\right|_{Z}=\left.D_{1}^{\nu_{0}+1}\left[2 D_{1} D_{3} \theta \cdot \theta-2 D_{3} \theta \cdot D_{1} \theta\right]\right|_{Z}=\left[-2\left(\nu_{0}+1\right)+2\right] D_{1}^{\nu_{0}+1} \theta$. $\left.D_{1} D_{3} \theta\right|_{Z}$, where the last equality follows because $\left.D_{3} \theta\right|_{Z}=0,\left.D_{1}^{\alpha} \theta\right|_{Z}=0$ for all $\alpha \leqslant \nu_{0}$. Hence, if $\left.D_{1} D_{3} \theta\right|_{Z} \not \equiv 0$, then $\left.D_{1}^{\nu_{0}+1} \theta\right|_{Z}=0$ and we are done. It only remains to consider the case where $\left.D_{1} D_{3} \theta\right|_{Z}=0$. If $D_{1}$ is in $T_{p}(Z)$ for $p$ generic in $Z$, the variety $Z$ is $D_{1}$-invariant, $\Theta$ is $D_{1}$-invariant along $Z$, and we are done; so we assume that, for $p$ generic in $Z$, the vector $D_{1}$ is not in $T_{p}(Z)$. Then, for dimensional reasons, $T_{p}(X)=\left\langle D_{1}, D_{2}, D_{3}, T_{p}(Z)\right\rangle$. Since $D_{1}^{2} \theta, D_{1} D_{2} \theta$ and $D_{1} D_{3} \theta$ all vanish on $Z$, we have $\left.D_{1} E \theta\right|_{Z}=0$ for all $E \in T_{0}(X)$. By Theorem 3.4, the tangent cone to $\Theta$ at $p$ is a pair of distinct hyperplanes. Therefore, for a generic $E \in T_{p}(X)$, we have that $\left.E D_{1} \theta\right|_{Z} \neq 0$. This is a contradiction.

LEMMA 3.8 (Shiota [S], Lemma A, p. 359). Let $\tau$ be a solution of the equation $P_{3} \tau=0$ in a neighborhood of a point $p_{0}$ in $\mathbb{C}^{n}$. If $D_{1}^{\alpha} \tau\left(p_{0}\right)=0$ for all integers $\alpha$, then $D_{1}^{\alpha} D_{2}^{\beta} \tau\left(p_{0}\right)=0$ for all integers $\alpha$ and $\beta$.

Proof. Let us denote by $L_{1}$ the (local) $D_{1}$-integral complex line through $p_{0}$. By hypothesis, $D_{1}^{\alpha} \tau\left(p_{0}\right)=0$, for all $\alpha$, thus $\left.\tau\right|_{L_{1}}=0$. We proceed by contradiction, i.e. we assume that there exists $b>0$ such that $\left.D_{2}^{b} \tau\right|_{L_{1}} \not \equiv 0$. Let

$$
\begin{align*}
\beta_{\gamma} & =\min \left\{\beta\left|D_{2}^{\beta} D_{3}^{\gamma} \tau\right|_{L_{1}} \not \equiv 0\right\}, \\
c & =\min \left\{\gamma \mid \beta_{\gamma}=0\right\},  \tag{3.8.1}\\
w & =\min \left\{\beta_{\gamma}+2 \gamma\right\}, \\
\sigma & =\max \left\{\gamma \mid \beta_{\gamma}+2 \gamma=w\right\},
\end{align*}
$$

where $\beta_{\gamma}$ and $c$ are allowed to be infinite. Note that $w \leqslant \beta_{0} \leqslant b<\infty, \sigma \leqslant \frac{1}{2} w<$ $\infty, w=\beta_{\sigma}+2 \sigma$ and $w \leqslant \beta_{\gamma}+2 \gamma$ for all $\gamma$. As $\left.\tau\right|_{L_{1}} \equiv 0$ we have $\beta_{0}>0$ and $c \geqslant 1$. Moreover $\left.D_{1}^{\alpha} D_{2}^{\beta} D_{3}^{\gamma} \tau\right|_{L_{1}}=0$, for all $\alpha, \beta<\beta_{\gamma}$. It follows that

$$
\begin{align*}
& \text { if } \beta+2 \gamma<w, \quad \text { then }\left.D_{1}^{\alpha} D_{2}^{\beta} D_{3}^{\gamma} \tau\right|_{L_{1}}=0,  \tag{3.8.2}\\
& \text { if } \gamma>\sigma \quad \text { and } \quad \beta+2 \gamma \leqslant w, \quad \text { then }\left.D_{1}^{\alpha} D_{2}^{\beta} D_{3}^{\gamma} \tau\right|_{L_{1}}=0 .
\end{align*}
$$

First, we prove that $\sigma=c$ (in particular $c<\infty$ ). It is clear that $\sigma \leqslant c$. If $\sigma<c$ then $\beta_{\sigma} \geqslant 1$, thus $2 \beta_{\sigma}-2 \geqslant 0$. Let us set $A_{0}=d_{4} \theta \cdot \theta, A_{1}=$ $-\frac{2}{3} D_{1}^{4} \theta \cdot \theta+\frac{8}{3} D_{1}^{3} \theta \cdot D_{1} \theta-2 D_{1}^{2} \theta \cdot D_{1}^{2} \theta, A_{2}=-2 D_{2}^{2} \theta \cdot \theta+2 D_{2} \theta \cdot D_{2} \theta$, $A_{3}=2 D_{1} D_{3} \theta \cdot \theta-2 D_{3} \theta \cdot D_{1} \theta$; so that $P_{3} \tau=A_{0}+A_{1}+A_{2}+A_{3}$. By 3.8.2 we have $\left.D_{2}^{2 \beta_{\sigma}-2} D_{3}^{2 \sigma}\left[A_{0}\right]\right|_{L_{1}}=\left.D_{2}^{2 \beta_{\sigma}-2} D_{3}^{2 \sigma}\left[A_{1}\right]\right|_{L_{1}}=\left.D_{2}^{2 \beta_{\sigma}-2} D_{3}^{2 \sigma}\left[A_{3}\right]\right|_{L_{1}}=0$. Therefore $0=\left.D_{2}^{2 \beta_{\sigma}-2} D_{3}^{2 \sigma} P_{3} \tau\right|_{L_{1}}=\left.D_{2}^{2 \beta_{\sigma}-2} D_{3}^{2 \sigma}\left[A_{2}\right]\right|_{L_{1}}=\binom{2 \sigma}{\sigma} \cdot\left[2\binom{2 \beta_{\sigma}-2}{\beta_{\sigma}-1}-2\binom{2 \beta_{\sigma}-2}{\beta_{\sigma}-2}\right]$. $\left.\left(D_{2}^{\beta_{\sigma}} D_{3}^{\sigma} \tau\right)^{2}\right|_{L_{1}}$, where the last equality follows by 3.8.2; this is a contradiction because $\left.D_{2}^{\beta_{\sigma}} D_{3}^{\sigma} \tau\right|_{L_{1}} \not \equiv 0$. Note that $\sigma=c$ implies $w=2 c$ and $\beta_{\gamma} \geqslant w-2 \gamma=$ $2 c-2 \gamma \geqslant 2$, for all $\gamma \leqslant c-1$. Let

$$
\begin{align*}
\tilde{w} & =\min \left\{\beta_{\gamma}+2 \gamma \mid \gamma<c\right\},  \tag{3.8.3}\\
\gamma_{0} & =\max \left\{\gamma \mid \gamma<c, \beta_{\gamma}+2 \gamma=\tilde{w}\right\} .
\end{align*}
$$

Note that, as $c \geqslant 1$ we have $\tilde{w} \leqslant \beta_{0}<\infty$. Thus, $\tilde{w}=\beta_{\gamma_{0}}+2 \gamma_{0}$. Moreover, as $\gamma_{0}<c$, we have $\beta_{\gamma_{0}} \geqslant 2$. We want to compute $\left.D_{2}^{\beta_{\gamma_{0}}-2} D_{3}^{c+\gamma_{0}} P_{3} \tau\right|_{L_{1}}$. By 3.8.3 we have

$$
\begin{align*}
& \text { if } \gamma<c \quad \text { and } \quad \beta+2 \gamma<\tilde{w}, \quad \text { then }\left.D_{1}^{\alpha} D_{2}^{\beta} D_{3}^{\gamma} \tau\right|_{L_{1}}=0,  \tag{3.8.4}\\
& \text { if } \gamma_{0}<\gamma<c \quad \text { and } \quad \beta+2 \gamma \leqslant \tilde{w}, \quad \text { then }\left.D_{1}^{\alpha} D_{2}^{\beta} D_{3}^{\gamma} \tau\right|_{L_{1}}=0 .
\end{align*}
$$

By 3.8.2 and 3.8.4 we get $\left.D_{2}^{\beta_{\gamma_{0}}-2} D_{3}^{c+\gamma_{0}}\left[A_{0}+A_{1}\right]\right|_{L_{1}}=0,\left.D_{2}^{\beta_{\gamma_{0}}-2} D_{3}^{c+\gamma_{0}}\left[A_{2}\right]\right|_{L_{1}}=$ $-\left.2\binom{c+\gamma_{0}}{c}\left(D_{2}^{\beta_{\gamma_{0}}} D_{3}^{\gamma_{0}} \tau\right) \cdot\left(D_{3}^{c} \tau\right)\right|_{L_{1}}$; if $\gamma_{0}<c-1$, then $\left.D_{2}^{\beta_{\gamma_{0}}-2} D_{3}^{c+\gamma_{0}}\left[A_{3}\right]\right|_{L_{1}}=0$; if $\gamma_{0}=c-1$, then $\left.D_{2}^{\beta_{\gamma_{0}}-2} D_{3}^{c+\gamma_{0}}\left[A_{3}\right]\right|_{L_{1}}=D_{2}^{\beta_{\gamma_{0}}-2}\left[\left(2\binom{c+\gamma_{0}}{c}-2\binom{c+\gamma_{0}}{\gamma_{0}}\right) D_{1} D_{3}^{c} \tau\right.$. $\left.D_{3}^{c} \tau\right]\left.\right|_{L_{1}}+\left.D_{2}^{\beta_{\gamma_{0}}-2}\left[\Sigma_{i+j=2 c, i \neq c}(\ldots) D_{1} D_{3}^{i} \tau \cdot D_{3}^{j} \tau\right]\right|_{L_{1}}=0$ (in fact, the coefficient $2\binom{c+\gamma_{0}}{c}-2\binom{c+\gamma_{0}}{\gamma_{0}}$ is zero $)$. Therefore, $0=\left.D_{2}^{\beta_{\gamma_{0}}-2} D_{3}^{c+\gamma_{0}} P_{3} \tau\right|_{L_{1}}=-2\binom{c+\gamma_{0}}{c}$ $\left.\left(D_{2}^{\beta_{\gamma_{0}}} D_{3}^{\gamma_{0}} \tau\right) \cdot\left(D_{3}^{c} \tau\right)\right|_{L_{1}}$. On the other hand, by 3.8.1 and 3.8.3, $\left(D_{2}^{\beta_{\gamma_{0}}} D_{3}^{\gamma_{0}} \tau\right)$. $\left.\left(D_{3}^{c} \tau\right)\right|_{L_{1}} \not \equiv 0$, thus a contradiction.

Proof. (of Theorem 3.2) By Lemma 3.7, $\Theta$ is $D_{1}$-invariant along $Z$; then, by Lemma 3.5, $Z$ is $D_{1}$-invariant. Hence, by Lemma 3.8, $\Theta$ is $\left\langle D_{1}, D_{2}\right\rangle$-invariant along $Z$; so, by Lemma $3.5, Z$ is $\left\langle D_{1}, D_{2}\right\rangle$-invariant.

We shall use the following algebraic computation about the possible series expansion of a solution of the K.P. equation. The following lemma is Lemma B from Shiota, restated in a way that is more convenient to our purpose.

LEMMA 3.9 (Shiota [S], Lemma B, p. 359). Let $(S, \mathcal{L})$ be a polarized abelian variety, $D_{1} \neq 0, D_{2}, \tilde{D}_{3} \in T_{0}(S)$. Assume that $S$ is generated by $\left\langle D_{1}, D_{2}\right\rangle$. Let $Y$ be a 2-dimensional disk with analytic coordinates $t$ and $\lambda$. Let $\tau$ be a nonzero section of $\mathcal{O}_{Y} \otimes H^{0}(S, \mathcal{L})$ and assume that
(i) $\quad P_{3}\left(D_{1}, D_{2}, \tilde{D}_{3}+\partial_{t} ; d\right) \tau=0$,
(ii) $\tau(t, \lambda, x)=\sum_{i, j \geqslant 0} \tau_{i, j}(x) \cdot t^{i} \lambda^{j}$,
where $x \in S$ (observe that $\tau_{i, j} \in H^{0}(S, \mathcal{L})$ for all $i$ and $j$ ). Also assume $\tau_{0, \rho}=0$, where $\rho:=\min \left\{j \mid \exists i: \tau_{i, j}(\cdot) \not \equiv 0\right\}$. Then there exist local sections at zero of $\mathcal{O}_{Y}$ and $\mathcal{O}_{Y} \otimes H^{0}(S, \mathcal{L}), f$ and $\psi$, such that

$$
\tau(t, \lambda, x)=\lambda^{\rho} \cdot f(t, \lambda) \cdot \psi(t, \lambda, x)
$$

where $\psi(0,0, \cdot) \not \equiv 0, f(0,0)=0$ and $f(\cdot, 0) \not \equiv 0$.
Proof. Step I (Shiota), we look for formal power series in $t$ and $\lambda, f$ and $\psi$ as in the lemma. Since $P_{3}\left(\lambda^{\rho} \cdot[\ldots]\right)=\lambda^{2 \rho} \cdot P_{3}(\ldots)$, we can assume $\rho=0$. Let $\nu=\max \left\{i \mid \tau_{i, 0}(\cdot) \equiv 0\right\}, f_{0}=t^{\nu}$ and $\bar{\tau}_{0}(t, x)=\Sigma_{i \geqslant \nu} \tau_{i, 0}(x) \cdot t^{i-\nu}$, so that $\tau=f_{0} \cdot \bar{\tau}_{0} \bmod (\lambda)$. Note that $P_{3}\left(\bar{\tau}_{0}\right)=0$, in fact $0=P_{3}(\tau)=t^{2 \nu} \cdot P_{3}\left(\bar{\tau}_{0}\right) \bmod (\lambda)$. Note also that $\bar{\tau}_{0}(0, x)=\tau_{\nu, 0}(x) \not \equiv 0$. It suffices to find constants and sections

$$
c_{i, j}, 0 \leqslant i \leqslant \nu-1,1 \leqslant j, \quad g_{i, j}(x) \in H^{0}(S, \mathcal{L}), i \geqslant \nu, j \geqslant 1,
$$

such that

$$
\begin{equation*}
\tau(t, \lambda, x)=\left(f_{0}+\sum_{j \geqslant 1} f_{j}(t) \cdot \lambda^{j}\right) \cdot\left(\bar{\tau}_{0}(t, x)+\sum_{j \geqslant 1} \bar{\tau}_{j}(t, x) \cdot \lambda^{j}\right), \tag{3.9.1}
\end{equation*}
$$

where, for $j \geqslant 1$, we define

$$
\begin{equation*}
f_{j}(t)=\sum_{i=0}^{\nu-1} c_{i, j} \cdot t^{i}, \quad \bar{\tau}_{j}(t, x)=\sum_{i \geqslant \nu} g_{i, j}(x) \cdot t^{i-\nu} \tag{3.9.2}
\end{equation*}
$$

We now proceed by induction: let $l$ be a positive integer, and assume that we found constants $c_{i, j}$, for all $1 \leqslant j \leqslant l-1, i \leqslant \nu-1$, and sections $g_{i, j}(x)$, for all $1 \leqslant j \leqslant l-1, i \geqslant \nu$, such that 3.9.1 holds modulo $\left(\lambda^{l}\right)$. Define $\tau^{\prime}(t, x)$ by

$$
\begin{align*}
\tau(t, \lambda, x)= & \left(f_{0}+\sum_{j=1}^{l-1} f_{j}(t) \cdot \lambda^{j}\right) \cdot\left(\bar{\tau}_{0}(t, x)+\sum_{j=1}^{l-1} \bar{\tau}_{j}(t, x) \cdot \lambda^{j}\right) \\
& +\lambda^{l} \cdot \tau^{\prime}(t, x) \quad \bmod \left(\lambda^{l+1}\right) . \tag{3.9.3}
\end{align*}
$$

We need to prove that there exist constants $c_{i, l}, i \leqslant \nu-1$, and sections $g_{i, l}, i \geqslant \nu$, such that

$$
\tau^{\prime}(t, x)=\sum_{i=0}^{\nu-1} c_{i, l} \cdot t^{i} \cdot \bar{\tau}_{0}(t, x)+\sum_{i \geqslant \nu} g_{i, l}(x) \cdot t^{i}
$$

In fact, defining $f_{l}, \bar{\tau}_{l}$ as 3.9.2 requires, it is clear that 3.9.1 holds modulo $\left(\lambda^{l+1}\right)$. We define $\tilde{P}_{3}(r, s)=\frac{1}{2}\left[P_{3}(r+s)-P_{3}(r)-P_{3}(s)\right]$. By substitution in 2.0 we get

$$
\begin{align*}
& \tilde{P}_{3}\left(D_{1}, D_{2}, \tilde{D}_{3}+\partial_{t} ; d\right)(r, s) \\
&=-\frac{1}{3}\left(D_{1}^{4} r \cdot s+D_{1}^{4} s \cdot r\right)+\frac{4}{3}\left(D_{1}^{3} r \cdot D_{1} s+D_{1}^{3} s \cdot D_{1} r\right) \\
&-2 D_{1}^{2} r \cdot D_{1}^{2} s-\left(D_{2}^{2} s \cdot r+D_{2}^{2} r \cdot s\right)+2 D_{2} r \cdot D_{2} s+d \cdot r \cdot s \\
&+\left(D_{1} \tilde{D}_{3} r \cdot s+D_{1} \tilde{D}_{3} s \cdot r\right)-\left(\tilde{D}_{3} r \cdot D_{1} s+\tilde{D}_{3} s \cdot D_{1} r\right) \\
&+\left(D_{1} \partial_{t} r \cdot s+D_{1} \partial_{t} s \cdot r\right)-\left(\partial_{t} r \cdot D_{1} s+\partial_{t} s \cdot D_{1} r\right) . \tag{3.9.4}
\end{align*}
$$

Note that $\tilde{P}_{3}$ is a symmetric $\mathbb{C}[\lambda]$-bilinear operator and that $P_{3}(r)=\tilde{P}_{3}(r, r)$. If $g=g(t, \lambda)$ does not depend on $x$, by a straightforward computation we obtain

$$
\begin{align*}
& \tilde{P}_{3}(g \cdot r, g \cdot s)=g^{2} \cdot \tilde{P}_{3}(r, s) \\
& \tilde{P}_{3}\left(t^{i} \cdot r, t^{j} \cdot s\right)=t^{i+j} \cdot \tilde{P}_{3}(r, s)+(i-j) t^{i+j-1} \cdot\left(D_{1} r \cdot s-D_{1} s \cdot r\right) \tag{3.9.5}
\end{align*}
$$

We define $g=g(t, \lambda)=\Sigma_{j=0}^{l-1} f_{j}(t) \cdot \lambda^{j}$ and $\phi(t, \lambda, x)=\Sigma_{j=0}^{l-1} \bar{\tau}_{j}(t, x) \cdot \lambda^{j}$, so that $\tau=g \cdot \phi+\lambda^{l} \cdot \tau^{\prime} \bmod \left(\lambda^{l+1}\right)$. Thus, by 3.9.5 the following equalities hold modulo $\left(\lambda^{l+1}\right): 0=P_{3}(\tau)=P_{3}\left(g \cdot \phi+\lambda^{l} \cdot \tau^{\prime}\right)=P_{3}(g \cdot \phi)+2 \tilde{P}_{3}\left(g \cdot \phi, \lambda^{l} \cdot \tau^{\prime}\right)=$ $g^{2} \cdot P_{3}(\phi)+2 \lambda^{l} \tilde{P}_{3}\left(g \cdot \phi, \tau^{\prime}\right)=g^{2} \cdot P_{3}(\phi)+2 \lambda^{l} \tilde{P}_{3}\left(t^{\nu} \cdot \bar{\tau}_{0}, \tau^{\prime}\right)$. In particular we
get $g^{2} \cdot P_{3}(\phi)=0 \bmod \left(\lambda^{l}\right)$. Since $g^{2}(t, \lambda)=t^{2 \nu} \bmod (\lambda)$ is nonzero, we get $P_{3}(\phi)=0 \bmod \left(\lambda^{l}\right)$. Since $g^{2} \cdot P_{3}(\phi)+2 \lambda^{l} \tilde{P}_{3}\left(t^{\nu} \cdot \bar{\tau}_{0}, \tau^{\prime}\right)=0 \bmod \left(\lambda^{l+1}\right)$ and (again) $g^{2}(t, \lambda)=t^{2 \nu} \bmod (\lambda)$ we get

$$
\begin{equation*}
\tilde{P}_{3}\left(t^{\nu} \cdot \bar{\tau}_{0}, \tau^{\prime}\right)=0 \quad \bmod \left(t^{2 \nu}\right) \tag{3.9.6}
\end{equation*}
$$

We now proceed by induction on $i$ : assume that $\tau^{\prime}(t, x)=\sum_{i=0}^{i_{0}-1} c_{i, l} \cdot t^{i} \cdot \bar{\tau}_{0}(t, x)+$ $\eta(x) \cdot t^{i_{0}}, \bmod \left(t^{i_{0}+1}\right)$, where $0 \leqslant i_{0} \leqslant \nu-1$. Since $\tilde{P}_{3}\left(\bar{\tau}_{0}, \bar{\tau}_{0}\right)=P_{3}\left(\bar{\tau}_{0}\right)=0$, by 3.9.5 we get $\tilde{P}_{3}\left(t^{\nu} \cdot \bar{\tau}_{0}, t^{i} \cdot \bar{\tau}_{0}\right)=0$. Thus, by substitution in 3.9.6 and (again) by 3.9.5 we get that the following equalities hold modulo $\left(t^{\nu+i_{0}}\right): 0=\tilde{P}_{3}\left(t^{\nu} \cdot \bar{\tau}_{0}, \Sigma_{i=0}^{i_{0}-1} c_{i, l}\right.$. $\left.\bar{\tau}_{0} \cdot t^{i}+\eta(x) \cdot t^{i_{0}}\right)=\tilde{P}_{3}\left(t^{\nu} \cdot \bar{\tau}_{0}, \eta(x) \cdot t^{i_{0}}\right)=\tilde{P}_{3}\left(t^{\nu} \cdot \bar{\tau}_{0}(0, x), \eta(x) \cdot t^{i_{0}}\right)=$ $\left(\nu-i_{0}\right) \cdot t^{\nu+i_{0}-1} \cdot\left[D_{1} \bar{\tau}_{0}(0, x) \cdot \eta(x)-D_{1} \eta(x) \cdot \bar{\tau}_{0}(0, x)\right]=-\left(\nu-i_{0}\right) \cdot t^{\nu+i_{0}-1}$. $\left[\bar{\tau}_{0}(0, x)\right]^{2} \cdot D_{1}\left(\eta(x) / \bar{\tau}_{0}(0, x)\right)$. It follows that $\eta(x) / \bar{\tau}_{0}(0, x)$ is $D_{1}$-invariant; on the other hand, the zeroes of $\bar{\tau}_{0}(0, \cdot)$ do not contain $D_{1}$-integral curves, otherwise, by 3.8 (applied to $\bar{\tau}_{0}$ ), we would have $\tau_{\nu, 0}(x)=\bar{\tau}_{0}(0, x)=0$. Thus $\eta(x)=c_{j_{0}, l} \cdot \bar{\tau}_{0}(0, x)$. It follows that $\tau^{\prime}(t, x)=\sum_{i=0}^{i_{0}} c_{i, l} \cdot t^{i} \cdot \bar{\tau}_{0}(t, x) \bmod \left(t^{i_{0}+1}\right)$, and we are done.

Step II, we prove that both $f$ and $\psi$ can be assumed to be regular functions. As $\psi(0,0, \cdot) \not \equiv 0$ we are allowed to fix an $x_{0}$ such that $\psi\left(0,0, x_{0}\right) \neq 0$ and consider the formal power series $q(t, \lambda)$ such that $\psi\left(t, \lambda, x_{0}\right) \cdot q(t, \lambda)=1$. Consider $\tilde{f}(t, \lambda):=f(t, \lambda) \cdot \psi\left(t, \lambda, x_{0}\right)$ and $\tilde{\psi}(t, \lambda, x):=\psi(t, \lambda, x) \cdot q(t, \lambda)$. It is clear that $\tau(t, \lambda, x)=\lambda^{\rho} \cdot \tilde{f}(t, \lambda) \cdot \tilde{\psi}(t, \lambda, x)$. As $\tilde{\psi}\left(t, \lambda, x_{0}\right)=1$ and $\tau\left(t, \lambda, x_{0}\right)$ are both convergent, $\tilde{f}(t, \lambda)$ is also convergent. Since $\tau(t, \lambda, x)$ and $\tilde{f}(t, \lambda)$ are convergent, $\tilde{\psi}(t, \lambda, x)$ is also convergent. Note that $t^{\nu}$ divides $\tilde{f}(t, 0)=0, \tilde{f}(t, 0) \not \equiv 0$ and $\tilde{\psi}(0,0, \cdot) \not \equiv 0$, i.e. the properties of $f$ and $\psi$ we need still hold for $\tilde{f}$ and $\tilde{\psi}$.

LEMMA 3.10. As usual, assume that $P_{i} \theta=0$, for all $i \leqslant m-1$. Let $\mathcal{W}$ be a component of the scheme $D_{1} \Theta$ and let p be a generic point of $\mathcal{W}_{\text {red }}$. Either $P_{m} \theta$ vanishes on $\mathcal{W}$, or there exist irreducible elements $h, k$ of $\mathcal{O}_{X, p}$ such that
(i) the ideal of $\mathcal{W}_{\text {red }}$ at $p$ is $(h, k)$;
(ii) the hypersurfaces $\{h=0\},\{k=0\}$ are smooth at $p$;
(iii) there exists an integer l such that $D_{3} \theta \notin\left(k, h^{l}\right)$ and $D_{1}^{\alpha} D_{2}^{\beta} \theta \in\left(k, h^{l}\right)$, for all $\alpha, \beta \geqslant 0$.
Proof. If $\Theta$ is not singular along $\mathcal{W}_{\text {red }}$ we take $k=\theta$ and we define $h$ as in 3.1.1. We proved that either $\left.P_{m} \theta\right|_{\mathcal{W}}=0$, or $h$ divides $D_{1} h$ in $\mathcal{O}_{\Theta, p}$. If $h$ divides $D_{1} h$ in $\mathcal{O}_{\Theta, p}$, by substitution in the expression of $P_{3} \theta$, we get $2 b=a+c$, where the notations are the ones of the formulas 3.1.1. If $b>a$ then $\left(D_{1}^{2}-D_{2}\right) \theta$, thus $P_{m} \theta$, vanishes on $\mathcal{W}$. It follows that either $\left.P_{m} \theta\right|_{\mathcal{W}}=0$, or $c<b<a$. Therefore the lemma holds with $l=b$. Let us turn to the case where $\Theta$ is singular along $\mathcal{W}_{\text {red }}$. By Theorem 3.4, we can write

$$
\theta=h \cdot k,
$$

where $h$ and $k$ satisfy (i), (ii) and belong to the analytic completion of $\mathcal{O}_{X, p}$. We prove that $h, k$ satisfy (iii). Then, taking $\tilde{h}$ and $\tilde{k}$ approximating $h$ and $k$ to the order $j(j \gg 0)$, one has that (i), (ii) and (iii) hold. Thus, we can assume that $h, k \in \mathcal{O}_{X, p}$. As there are no $D_{1}$-invariant components of $\Theta$, the element $h$ does not divide $D_{1} h$ in $\mathcal{O}_{X, p}$, likewise $k$ does not divide $D_{1} k$ in $\mathcal{O}_{X, p}$, (and similarly for $D_{2}$ ) and we can write

$$
\begin{aligned}
& D_{1} h=\varepsilon_{1} \cdot k^{a}+g_{1} \cdot h, \\
& D_{1} k=\tilde{\varepsilon}_{1} \cdot h^{\tilde{a}}+\tilde{g}_{1} \cdot k, \\
& D_{2} h=\varepsilon_{2} \cdot k^{b}+g_{2} \cdot h, \\
& D_{2} k=\tilde{\varepsilon}_{2} \cdot h^{\tilde{b}}+\tilde{g}_{2} \cdot k,
\end{aligned}
$$

where $\varepsilon_{1}, \tilde{\varepsilon}_{1}, \varepsilon_{2}, \tilde{\varepsilon}_{2}$ are invertible, $a, \tilde{a}, b, \tilde{b} \geqslant 1$. Note that, by 3.0 , we are allowed to assume $a \geqslant b, \tilde{a} \geqslant \tilde{b}$. Note that $D_{1}^{\alpha} D_{2}^{\beta} h, D_{1}^{\alpha} D_{2}^{\beta} k \in(h, k)$, for all $\alpha, \beta$, since, by Theorem 3.2, $\mathcal{W}_{\text {red }}$ is $\left\langle D_{1}, D_{2}\right\rangle$-invariant. It follows that

$$
\begin{aligned}
& D_{1}^{\alpha} \theta=D_{1}^{\alpha}(h \cdot k) \in\left(h \cdot k, k^{a+1}, h^{\tilde{a}+1}\right), \quad \forall \alpha \geqslant 0 \\
& D_{1}^{\alpha} D_{2}^{\beta} \theta=D_{1}^{\alpha} D_{2}^{\beta}(h \cdot k) \in\left(h \cdot k, k^{b+1}, h^{\tilde{b}+1}\right), \quad \forall \alpha, \beta \geqslant 0 .
\end{aligned}
$$

We now claim that either $D_{3} \theta \notin\left(h \cdot k, k^{b+1}, h^{\tilde{b}+1}\right)$, or $\left.P_{m} \theta\right|_{\mathcal{W}}=0$. Since $(h$. $\left.k, k^{b+1}, h^{\tilde{b}+1}\right)=\left(h, k^{b+1}\right) \cap\left(k, h^{\tilde{b}+1}\right)$ we have that the previous claim (up to interchanging the roles played by $h$ and $k$ ) implies the lemma. So, let us prove our claim. First, observe that if $D_{3} \theta \in\left(h, k^{b+1}\right) \cap\left(k, h^{\tilde{b}+1}\right)$ then by substitution in 2.0 we get $0=P_{3} \theta=2 \cdot \tilde{\gamma}^{2} \cdot h^{2 \tilde{b}+2}, \bmod \left(k, h^{\tilde{a}+\tilde{b}+2}\right)$. Thus $2 \tilde{b}+2 \geqslant \tilde{a}+\tilde{b}+2$. Since $\tilde{a}>\tilde{b}$ we get $\tilde{b}=\tilde{a}$. Similarly, computing $P_{3} \theta$ modulo $\left(h, k^{a+b+2}\right)$ we get $a=b$. It follows that $\left(D_{1}^{2}-D_{2}\right) \theta \in\left(h \cdot k, k^{a+1}, h^{\tilde{a}+1}\right)$. Note that the ideal $I_{D_{1} \Theta}$ is $\left(h \cdot k, \varepsilon_{1} k^{a+1}+\tilde{\varepsilon}_{1} h^{\hat{a}+1}\right)$, where $\varepsilon_{1}, \tilde{\varepsilon}_{1}$ are invertible. Thus $I_{D_{1} \Theta} \supset(h$. $k, k^{a+2}, h^{\tilde{a}+2}$ ). Since $P_{3} \theta=\cdots=P_{m-1} \theta=0$ by inductive hypothesis, by the first one of formulas 2.5 (with $s=m$ ) we get $\left.P_{m} \theta\right|_{\mathcal{W}}=-\left(D_{1}^{2}-D_{2}\right) \theta \cdot \tilde{\Delta}_{m-1} \theta$, where we keep the notation of the formulas 2.5 . We claim that it suffices to prove that $\tilde{\Delta}_{m-1} \theta \in(h, k)$. Indeed, since $\left(D_{1}^{2}-D_{2}\right) \theta$ is in $\left(h \cdot k, k^{a+1}, h^{\tilde{a}+1}\right)$, if $\tilde{\Delta}_{m-1} \theta$ is in $(h, k)$, then $\left.P_{m} \theta\right|_{\mathcal{W}}=-\left(D_{1}^{2}-D_{2}\right) \theta \cdot \tilde{\Delta}_{m-1} \theta \in\left(h \cdot k, k^{a+2}, h^{\tilde{a}+2}\right) \subset I_{D_{1} \Theta}$, and we are done. By inductive hypothesis, the left-hand side of the first formula 2.5 (with $s=m-1$ ) is zero; it follows that the right hand side must be zero, in particular we get

$$
\begin{equation*}
-\left(D_{1}^{2}-D_{2}\right) \theta \cdot \tilde{\Delta}_{m-2} \theta-D_{1} \theta \cdot\left(\tilde{\Delta}_{m-1}+2 D_{1} \tilde{\Delta}_{m-2}\right) \theta=0 \bmod (\theta) \tag{3.10.1}
\end{equation*}
$$

It follows that $\tilde{\Delta}_{m-2} \theta \in(h, k)$, otherwise we would have $-\left(D_{1}^{2}-D_{2}\right) \theta \in I_{D_{1} \Theta}$ and we would be done. We now compute the left-hand side of 3.10 .1 modulo the ideal $\left(h \cdot k, k^{a+2}, h^{\tilde{a}+2}\right)$ (note that this ideal contains $(\theta)=(h \cdot k)$ ). Since $\tilde{\Delta}_{m-2} \theta \in$
$(h, k)$ and $\left(D_{1}^{2}-D_{2}\right) \theta \in\left(h \cdot k, k^{a+1}, h^{\tilde{a}+1}\right)$ we have that $\left(D_{1}^{2}-D_{2}\right) \theta \cdot \tilde{\Delta}_{m-2} \theta$ is in $\left(h \cdot k, k^{a+2}, h^{\tilde{a}+2}\right)$. Since $D_{1} \theta$ is in $\left(h \cdot k, k^{a+1}, h^{\tilde{a}+1}\right)$ and $\tilde{\Delta}_{m-2} \theta$, hence $D_{1} \tilde{\Delta}_{m-2} \theta$, is in $(h, k)$, also $D_{1} \theta \cdot D_{1} \tilde{\Delta}_{m-2} \theta$ is in $\left(h \cdot k, k^{a+2}, h^{\tilde{a}+2}\right)$. Therefore, by 3.10 .1

$$
\begin{equation*}
-D_{1} \theta \cdot \tilde{\Delta}_{m-1} \theta \in\left(h \cdot k, k^{a+2}, h^{\tilde{a}+2}\right) \tag{3.10.2}
\end{equation*}
$$

Since $D_{1} \theta=D_{1}(h \cdot k)=\varepsilon \cdot k^{a+1}+\tilde{\varepsilon} \cdot h^{\tilde{a}+1} \bmod (h \cdot k)$ it follows that $D_{1} \theta$ is not in $\left(h \cdot k, k^{a+2}, h^{\tilde{a}+2}\right)$. Therefore, by 3.10.2, $\tilde{\Delta}_{m-1} \theta$ is in $(h, k)$ and we are done.

## 4. End of the proof

Let us go back to the K.P. hierarchy. We assume, by induction, that we found invariant vector fields $D_{1}, \ldots, D_{m-1}$, and constants $d_{4}, \ldots, d_{m}$ such that

$$
P_{i}\left(D_{1}, \ldots, D_{i} ; d_{4}, \ldots, d_{i+1}\right) \theta=0, \quad \forall i \leqslant m-1 .
$$

We need to find an invariant vector field $D_{m}$ and a constant $d_{m+1}$ such that $P_{m}\left(D_{1}, \ldots, D_{m} ; d_{4}, \ldots, d_{m+1}\right) \theta=0$.

Let $P_{m} \theta:=P_{m}\left(D_{1}, \ldots, D_{m-1}, 0 ; d_{4}, \ldots, d_{m}, 0\right) \theta$. Recall that if $\left.P_{m} \theta\right|_{D_{1} \Theta}=0$ we are done by Remark 2.6. We proved that then the only components of the scheme $D_{1} \Theta$ where $P_{m} \theta$ might not vanish are, set-theoretically, $\left\langle D_{1}, D_{2}\right\rangle$-invariant. In order to conclude our proof of Shiota's Theorem we proceed by contradiction. Let $\mathcal{W}$ be a component of $D_{1} \Theta$ such that $P_{m} \theta \mid \mathcal{W} \neq 0$. Thus, $\mathcal{W}_{\text {red }}$ is $\left\langle D_{1}, D_{2}\right\rangle$-invariant.

We denote by $X^{\prime}$ the $\left\langle D_{1}, D_{2}\right\rangle$-invariant minimal abelian subvariety of $X$. Since $D_{1} \neq 0$ we have $X^{\prime} \neq 0$, on the other hand $\mathcal{W}$ contains a translate of $X^{\prime}$, therefore $X^{\prime} \neq X$. Note that $\mathcal{W}_{\text {red }}$ is $T_{0}\left(X^{\prime}\right)$-invariant. Let $X^{\prime \prime}$ be the complement of $X^{\prime}$ in $X$, relative to the polarization $\Theta$. This means that $X^{\prime \prime}$ is the connected component containing zero of the kernel of the composite map $X \rightarrow \operatorname{Pic}^{0}(X) \rightarrow \operatorname{Pic}^{0}\left(X^{\prime}\right)$. Here the first map sends $x$ to the class of $\Theta_{x}-\Theta$, and the second map is the natural restriction.

Let $\mathcal{R}:=\left(\mathcal{W} \cap X^{\prime \prime}\right)_{\text {red }}$. Note that $\mathcal{W}_{\text {red }}$ is the $T_{0}\left(X^{\prime}\right)$-span of $\mathcal{R}$, i.e. $\mathcal{W}_{\text {red }}=$ $\mathcal{R}+X^{\prime}$, and that $\mathcal{R}$ has codimension 2 in $X^{\prime \prime}$. In the sequel we shall work on $X^{\prime \prime} \times X^{\prime}$. Observe that $\theta$ is naturally a theta function also for $\pi^{\star} \mathcal{O}_{X}(\Theta)$ via the sum map $\pi: X^{\prime \prime} \times X^{\prime} \rightarrow X$. In fact, as $T_{0}\left(X^{\prime \prime}\right) \times T_{0}\left(X^{\prime}\right) \cong T_{0}(X)$ (canonically), there is a canonical identification of the universal cover of $X^{\prime \prime} \times X^{\prime}$ with the one of $X$ which commutes with the isogeny $\pi: X^{\prime \prime} \times X^{\prime} \rightarrow X,\left(x^{\prime \prime}, x^{\prime}\right) \mapsto x^{\prime \prime}+x^{\prime}$. In particular, this property allows us to write $\theta$ instead of $\pi^{\star} \theta$ while working on $X^{\prime \prime} \times X^{\prime}$.

Let us fix general points $b \in \mathcal{R}, x^{\prime} \in X^{\prime}$, so that $p:=\left(b, x^{\prime}\right)$ is a general point of $\pi^{-1}\left(\mathcal{W}_{\text {red }}\right)$. Let us decompose $D_{3}$ as $D_{3}^{\prime}+D_{3}^{\prime \prime}$, where $D_{3}^{\prime} \in T_{0}\left(X^{\prime}\right), D_{3}^{\prime \prime} \in T_{0}\left(X^{\prime \prime}\right)$. Since $X^{\prime}$ is generated by the $\left\langle D_{1}, D_{2}\right\rangle$-flow, $D_{3}^{\prime \prime}$ is nonzero by Lemma 3.10 (iii). Let $L$ be the (analytic) germ at zero of the $D_{3}^{\prime \prime}$-integral line in $X^{\prime \prime}$ through zero, let
$\mathcal{C}$ be the germ at $b$ of a smooth curve in $X^{\prime \prime}$ meeting $L+b$ transversally only at $b$, and let $Y$ be the surface $\mathcal{C}+L$ in $X^{\prime \prime}$. Let $\Omega$ be the subvariety $Y \times X^{\prime}$ of $X^{\prime \prime} \times X^{\prime}$.

Let $\lambda$ be a parameter on $\mathcal{C}$ vanishing at $b$ and let $t$ be the coordinate on $L$ (vanishing at zero) with $\partial_{t}=D_{3}^{\prime \prime}$. Thus $\lambda, t$ are parameters on $Y$, likewise they are naturally parameters on the product $\Omega=Y \times X^{\prime}$. Note that $\left.\left[D_{1}^{\alpha} D_{2}^{\beta} D_{3}^{\gamma}(\ldots)\right]\right|_{\Omega}=$ $D_{1}^{\alpha} D_{2}^{\beta} D_{3}^{\gamma}\left(\left.\ldots\right|_{\Omega}\right)$. On $\Omega$ we write

$$
\begin{equation*}
\theta(t, \lambda, x)=\sum_{i, j \geqslant 0} \tau_{i, j}(x) \cdot t^{i} \cdot \lambda^{j} \tag{4.1}
\end{equation*}
$$

where $x$ is in $X^{\prime}$. We recall that by the definition of the complement of $X^{\prime}$ there is an isomorphism $\left.\left.\left(t_{x}^{*} \mathcal{O}(\Theta)\right)\right|_{X^{\prime}} \cong \mathcal{O}(\Theta)\right|_{X^{\prime}}$ for all $x \in X^{\prime \prime}$, where $t_{x}$ denotes the translation $y \mapsto y+x$. Thus the $\theta(t, \lambda, \cdot)$ 's are sections of the restriction $\left.\Theta\right|_{X^{\prime}}$. Note that $\tau_{i, j}$ depends on the point $b$ and the curve $\mathcal{C}$ chosen, and that $\tau_{i, j}=(1 / i!\cdot j!)\left(\left(\partial^{j} / \partial \lambda^{j}\right) D_{3}^{\prime \prime i} \theta\right)(0,0, \cdot)$ is in $H^{0}\left(X^{\prime},\left.\Theta\right|_{X^{\prime}}\right)$. Indeed, since the $\theta(t, \lambda, \cdot)$ 's are sections of the restriction $\left.\Theta\right|_{X^{\prime}}$, so are its derivatives with respect to $t$ and $\lambda$.

We use Lemmas 3.9 and 3.10 to reach a contradiction. Our analysis is divided naturally in two cases which correspond to whether the variety $\mathcal{R}$ is not $D_{3}^{\prime \prime}-$ invariant, or it is $D_{3}^{\prime \prime}$-invariant.

Let us first assume that $\mathcal{R}$ is not $D_{3}^{\prime \prime}$-invariant. Let us choose $\mathcal{C}$ in such a way that it meets $\mathcal{R}$ transversally only at $b, \partial_{\lambda} \notin\left\langle T_{b}(\mathcal{R}), D_{3}^{\prime \prime}\right\rangle$. This is possible because $\mathcal{R}$ has codimension 2 in $X^{\prime \prime}$. We have $Y \cap \mathcal{R}=\{\lambda=t=0\}$, thus $\Omega \cap \pi^{-1}\left(\mathcal{W}_{\text {red }}\right)=\{\lambda=t=0\} \times X^{\prime}$. It follows that $\tau_{i, 0} \not \equiv 0$ for some $i$, and, moreover, $\tau_{0,0}(x)=0$ (otherwise we would not have $\left.\theta\right|_{b+X^{\prime}}=0$ ). Because of Lemma 3.9 we have $\theta=f(t, \lambda) \cdot \psi(t, \lambda, x)$, where $f(0,0)=0$. We have $\Omega \cap \pi^{-1} \mathcal{W}=\Omega \cap\{\theta=0\} \cap\left\{D_{1} \theta=0\right\} \supseteq \Omega \cap\{f=0\}$. Moreover, since $f(0,0)=0$, it follows that $\Omega \cap \pi^{-1} \mathcal{W}$ has codimension 1 in $\Omega$. This contradicts $\Omega \cap \pi^{-1}\left(\mathcal{W}_{\text {red }}\right)=\{\lambda=t=0\} \times X^{\prime}$.

Let us now assume that $\mathcal{R}$ is $D_{3}^{\prime \prime}$-invariant. Choose $\mathcal{C}$, depending on the point $x^{\prime}$, in such a way that it meets $\mathcal{R}$ transversally only at $b$, and $\mathcal{C} \times\left\{x^{\prime}\right\} \subset\{k=0\}$, where $k$ is as in Lemma 3.10. Since the loci $\{h=0\}$ and $\{k=0\}$ are transverse by 3.10 (i), and $\mathcal{C}$ meets $\mathcal{R}$ transversally at $b$, we may assume that $\lambda$ is the restriction of $h$ to $\mathcal{C} \times\left\{x^{\prime}\right\} \cong \mathcal{C}$. We have that $\Omega \cap \pi^{-1}\left(\mathcal{W}_{\text {red }}\right)=\{\lambda=0\}$. Let $\rho=\min \left\{j \mid \exists i: \tau_{i, j}(\cdot) \not \equiv 0\right\}$. Note that, as $\mathcal{C}$ depends on $x^{\prime}, \tau_{i, j}$ depends on $x^{\prime}$. We want to prove that $\tau_{0, \rho}=0$. For this it suffices to prove that $D_{1}^{\alpha} D_{2}^{\beta} \tau_{0, \rho}\left(x^{\prime}\right)=0$, for all $\alpha$ and $\beta$, since the flow generated by $D_{1}$ and $D_{2}$ is dense in $X^{\prime}$. Since $\mathcal{C}=\{t=0\}$, by 4.1 we have

$$
\begin{array}{ll}
\left.D_{1}^{\alpha} D_{2}^{\beta} \theta\right|_{\mathcal{C} \times X^{\prime}}=D_{1}^{\alpha} D_{2}^{\beta} \theta(0, \lambda, \cdot)=\lambda^{\rho} \cdot D_{1}^{\alpha} D_{2}^{\beta} \tau_{0, \rho}(\cdot), & \bmod \left(\lambda^{\rho+1}\right),  \tag{4.2}\\
\left.D_{3} \theta\right|_{\mathcal{C} \times X^{\prime}}=D_{3} \theta(0, \lambda, \cdot)=0, & \bmod \left(\lambda^{\rho}\right)
\end{array}
$$

By Lemma 3.10, in the local ring $\mathcal{O}_{\{k=0\}, p}$ we have that $D_{1}^{\alpha} D_{2}^{\beta} \theta \in(h)^{l}, D_{3} \theta \notin$ $(h)^{l}$, for some $l$, where $h$ is as in 3.10. Since $\lambda$ is the restriction of $h$ to $\mathcal{C} \times\left\{x^{\prime}\right\} \cong \mathcal{C}$,
in the local ring $\mathcal{O}_{\mathcal{C} \times\left\{x^{\prime}\right\}, p}$, we have that $D_{1}^{\alpha} D_{2}^{\beta} \theta \in(\lambda)^{l}, D_{3} \theta \notin(\lambda)^{l}$. We have $l>\rho$ by the second formulas in 4.2. On the other hand, since $l>\rho$ we must have $D_{1}^{\alpha} D_{2}^{\beta} \tau_{0, \rho}\left(x^{\prime}\right)=0$ for all $\alpha$ and $\beta$, by the first formulas in 4.2. Since $X^{\prime}$ is generated by the $\left\langle D_{1}, D_{2}\right\rangle$-flow and $D_{1}^{\alpha} D_{2}^{\beta} \tau_{0, \rho}\left(x^{\prime}\right)=0$ for all $\alpha$ and $\beta$, we get $\tau_{0, \rho}=0$. Hence we can apply Lemma 3.9. It follows that the equality 4.1 takes the form $\theta(t, \lambda, x)=\lambda^{\rho} \cdot f(t, \lambda) \cdot \psi(t, \lambda, x)$, so that $f$ divides both $\left.\theta\right|_{\Omega}$ and $\left.D_{1} \theta\right|_{\Omega}$. Therefore, $\Omega \cap \pi^{-1}\left(\mathcal{W}_{\text {red }}\right) \supset \Omega \cap\{f=0\}$. By Lemma 3.9, $f(0,0)=0$ and $f(\cdot, 0) \not \equiv 0$. As $\Omega \cap \pi^{-1}\left(\mathcal{W}_{\text {red }}\right) \supset \Omega \cap\{f=0\}$, the locus $\Omega \cap \pi^{-1}\left(\mathcal{W}_{\text {red }}\right)$ contains (locally at $p$ ) a component which is not the component $\{\lambda=0\}$. This contradicts the fact that, locally at $p, \Omega \cap \pi^{-1}\left(\mathcal{W}_{\text {red }}\right)=\{\lambda=0\}$.

REMARK 4.3. If one could show that $\mathcal{W}$ (not only its underlying reduced scheme $\mathcal{W}_{\text {red }}$ ) were $\left\langle D_{1}, D_{2}\right\rangle$-invariant it would easily follow by the very expression of $P_{m} \theta$ that $P_{m} \theta$ vanishes on $\mathcal{W}$. In fact, in this case, $\theta(z+a)$ (where $a \in X^{\prime}$ ) would vanish on $\mathcal{W}$. Hence, $D_{1}^{2} \theta$ and $D_{2} \theta$ would vanish on $\mathcal{W}$ as well.

## Acknowledgements

This paper is the core of my thesis at the University of Rome. I heartily thank my advisor Enrico Arbarello for being very important in my mathematical development and introducing me to this problem. I am grateful to Riccardo Salvati Manni and Corrado De Concini for many stimulating conversations on the subject of this paper. I am grateful to Olivier Debarre for pointing out a mistake in a previous version of this paper, and also to the referee who suggested several improvements.

## References

[A] Arbarello, E.: Fay's trisecant formula and a characterization of Jacobian Varieties, Proceedings of Symposia in Pure Mathematics 46 (1987).
[AD1] Arbarello, E. and De Concini, C.: On a set of equations characterizing Riemann matrices, Ann. of Math. 120 (1984) 119-140.
[AD2] Arbarello, E. and De Concini, C.: Another proof of a conjecture of S. P. Novikov on periods of abelian integrals on Riemann surfaces, Duke Math. J. 54 (1987) 163-178.
[AD3] Arbarello, E. and De Concini, C.: Geometrical aspects of the Kadomtsev-Petviashvili equation, L.N.M. 1451 (1990) 95-137.
[De] Debarre, O.: Trisecant lines and Jacobians, Journal of Algebraic Geometry 1 (1992) 5-14.
[Do] Donagi, R.: The Schottky problem, L.N.M. 1337 (1989) 84-137.
[Du] Dubrovin, B.A.: Theta functions and non-linear equations, Russian Math. Surveys 36(2) (1981) 11-92.
[EL] Ein, L. and Lazarsfeld, R.: Singularities of theta divisors, and the birational geometry of irregular varieties, Preprint (alg-geom/9603017).
[F] Fay, J.: Theta Functions on Riemann Surfaces, L.N.M. 352 (1973).
[G] Gunning, R. C.: Some curves in abelian varieties, Invent. Math. 66 (1982) 377-389.
[GG] Van Geemen, B. and van der Geer, G.: Kummer varieties and the moduli spaces of abelian varieties, Amer. J. of Math. 108 (1986) 615-642.
[Ko] Kollár, J.: Shafarevich Maps and Automorphic Forms, Princeton Univ. Press, 1995.
[Kr] Krichever, I. M.: Methods of Algebraic Geometry in the theory of nonlinear equations, Russian Math. Surveys 32 (1977) 185-213.
[Ma] Marini, G.: A characterization of hyperelliptic Jacobians, Manuscripta Mathematica 79 (1993) 335-341.
[Mu] Mumford, D.: An algebro-geometric construction of commuting operators and of solutions to the Toda lattice equation, Korteweg-de Vries equation and related non-linear equation, Proc. Intern. Sympos. Alg. Geometry, Kyoto (1977).
[S] Shiota, T.: Characterization of Jacobian varieties in terms of soliton equations, Invent. Math. 83 (1986) 333-382.
[W] Welters, G.: A criterion for Jacobi varieties, Ann. Math. 120 (1984) 497-504.

