THE STABLE SET POLYTOPE OF QUASI-LINE GRAPHS*

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It is a long standing open problem to find an explicit description of the stable set polytope of *claw-free graphs*. Yet more than 20 years after the discovery of a polynomial algorithm for the maximum stable set problem for claw-free graphs, there is even no conjecture at hand today.

Such a conjecture exists for the class of *quasi-line graphs*. This class of graphs is a proper superclass of line graphs and a proper subclass of claw-free graphs for which it is known that not all facets have 0/1 normal vectors. The *Ben Rebea conjecture* states that the stable set polytope of a quasi-line graph is completely described by *clique-family* inequalities. Chudnovsky and Seymour recently provided a decomposition result for claw-free graphs and proved that the Ben Rebea conjecture holds, if the quasi-line graph is not a *fuzzy circular interval graph*.

In this paper, we give a proof of the Ben Rebea conjecture by showing that it also holds for fuzzy circular interval graphs. Our result builds upon an algorithm of Bartholdi, Orlin and Ratliff which is concerned with integer programs defined by circular ones matrices.

1. Introduction

A graph G is *claw-free* if no vertex has three pairwise nonadjacent neighbors. Line graphs are claw free and thus the weighted stable set problem for a claw-free graph is a generalization of the weighted matching problem of a graph. While the general stable set problem is NP-complete, it can be solved in polynomial time on a claw-free graph [22,31] even in the weighted

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case [24, 25] see also [34]. These algorithms are extensions of Edmonds' [11, 10] matching algorithms.

The stable set polytope STAB(G) is the convex hull of the characteristic vectors of stable sets of the graph G. The polynomial *equivalence of separation and optimization* for rational polyhedra [17, 28, 19] provides a polynomial time algorithm for the separation problem for STAB(G), if G is claw-free. However, this algorithm is based on the ellipsoid method [20] and no explicit description of a set of inequalities is known that determines STAB(G) in this case. This apparent asymmetry between the algorithmic and the polyhedral status of the stable set problem in claw-free graphs gives rise to the challenging problem of providing a "...decent linear description of STAB(G)" [18], which is still open today. In spite of results characterizing the rank-facets [13] (facets with 0/1 normal vectors) of claw-free graphs, or giving a compact lifted formulation for the subclass of distance claw-free graphs [29], the structure of the general facets for claw-free graphs is still not well understood and even no conjecture is at hand.

The matching problem [10] is a well known example of a combinatorial optimization problem in which the optimization problem on the one hand and the facets on the other hand are well understood. This polytope can be described by a system of inequalities in which the coefficients on the lefthand-side are 0/1. This property of the matching polytope does *not* extend to the polytope STAB(G) associated with a claw-free graph. In fact, Giles and Trotter [15] show that for each positive integer a, there exists a claw-free graph G such that STAB(G) has facets with $a/(a+1)$ normal vectors. Furthermore they show that there exist facets whose normal vectors have up to 3 different coefficients (indeed up to 5 as it is shown in [21]). Perhaps this is one of the reasons why providing a description of STAB(G) is not easy, since 0/1 normal vectors can be interpreted as subsets of the set of nodes, whereas such an interpretation is not immediate if the normal vectors are not 0/1.

A graph is *quasi-line*, if the neighborhood of any vertex partitions into two cliques. The complement of quasi-line graphs are called *near-bipartite* and an interesting *polyhedral* characterization of near-bipartite graphs is given in [23]; also a linear description of their stable set polytope has been given in [35]. The class of quasi-line graphs is a proper superclass of line graphs and a proper subclass of the class of claw-free graphs. Interestingly also for this class of graphs there are facets with $a/(a+1)$ normal vectors, for any nonnegative integer a [15], but no facet whose normal vector has more than 2 different coefficients is known for this class.

Clique family inequalities and the Ben Rebea conjecture

We now describe the clique-family inequalities introduced in [27]. Our main result is a proof of the Ben Rebea conjecture, which essentially says that this proper generalization of the *odd-set inequalities* [10] which describe the matching polytope, together with the nonnegativity and clique inequalities, describe the stable set polytope of a quasi-line graph.

Let $\mathcal{F} = \{K_1, \ldots, K_n\}$ be a set of cliques, $1 \leq p \leq n$ be integral and $r = n$ mod p. Let $V_{p-1} \subseteq V(G)$ be the set of vertices covered by exactly $(p-1)$ cliques of $\mathcal{F}$ and $V_{\geq p} \subseteq V(G)$ the set of vertices covered by p or more cliques of $\mathcal{F}$. The inequality

$$(1) \qquad (p - r - 1) \sum_{v \in V_{p-1}} x(v) + (p - r) \sum_{v \in V_{\geq p}} x(v) \leq (p - r) \left\lfloor \frac{n}{p} \right\rfloor$$

is valid [27] for STAB(G) and is called the *clique family inequality* associated with $\mathcal{F}$ and p.

Clique family inequalities are a generalization of *odd-set inequalities* [10] which are part of the description of the *matching polytope*. This can be seen as follows. Suppose that the graph $G = (V(G), E(G))$ is the line graph of the graph $H = (V(H), E(H))$ and let $U \subseteq V(H)$ be an odd subset of the nodes of H.

The odd-set inequality defined by U is the inequality

$$(2) \qquad \sum_{e \in E(U)} x(e) \leq \lfloor |U|/2 \rfloor$$

which is valid for all characteristic vectors $\chi \in \{0, 1\}^{E(H)}$ of matchings in H. Here, $E(U) \subseteq E(H)$ is the subset of edges of H which have both endpoints in U.

This inequality is a clique-family inequality for the stable-set polytope of G, via the following construction. Each vertex $v \in U$ yields a clique K_v in the line graph G of H consisting of the edges $e \in E(H)$, which are incident to v. The family of cliques $\mathcal{F}$ will consist of those cliques. Furthermore we let $p = 2$. Since $|U|$ is odd the remainder r is 1. Furthermore, the vertices of G which are in $V_{\geq p}$ are exactly the edges of H which have both endpoints in $U \subseteq V(H)$. The clique family inequality corresponding to $\mathcal{F}$ and p is therefore the odd-set inequality

$$(3) \qquad \sum_{v \in E(U)} x(v) \leq \lfloor |U|/2 \rfloor.$$

Ben Rebea [30] considered the problem to study STAB(G) for quasi-line graphs. Oriolo [27] formulated a conjecture inspired by his work.

Conjecture (Ben Rebea conjecture [27]). *The stable set polytope of a quasi-line graph $G = (V, E)$ may be described by the following inequalities:*

(i) $x(v) \geq 0$ *for each $v \in V$*
(ii) $\sum_{v \in K} x(v) \leq 1$ *for each maximal clique K*
(iii) *inequalities (1) for each family $\mathcal{F}$ of maximal cliques and each integer p with $|\mathcal{F}| > 2p \geq 4$ and $|\mathcal{F}| \mod p \neq 0$.*

In this paper we prove that Ben Rebea Conjecture holds true. This is done by establishing the conjecture for *fuzzy circular interval graphs*, a class introduced by Chudnovsky and Seymour [6]. This settles the result, since Chudnovsky and Seymour showed that the conjecture holds if G is quasi-line and not a fuzzy circular interval graph. Interestingly, since all the facets are rank for this latter class of graphs, the quasi-line graphs that "produce" non-rank facets are the fuzzy circular interval graphs. We recall that a *rank* inequality is an inequality whose normal vector has only 0/1 coefficients.

We first show that we can focus our attention on *circular interval graphs* [6], a subclass of fuzzy circular interval graphs. The weighted stable set problem over a circular interval graph may be formulated as a packing problem $\max\{cx \mid Ax \leq b, x \in \mathbb{Z}_{\geq 0}^n\}$, where $b = \mathbf{1}$ and $A \in \{0,1\}^{m \times n}$ is a *circular ones matrix*, i.e., the columns of A can be permuted in such a way that the ones in each row appear consecutively. Here the last and first entry of a row are also considered to be consecutive. Integer programs of this sort with general right-hand side $b \in \mathbb{Z}^m$ have been studied by Bartholdi, Orlin and Ratliff [3]. From this, we derive a separation algorithm which is based on the computation of a cycle with negative length in a suitable directed graph D, thereby extending a recent result of Gijswijt [14]. We then concentrate on packing problems with right-hand side $b = \alpha \mathbf{1}$, where α is an integer. By studying the structure of the cycles of D with negative length, we show that each facet of the convex hull of integer feasible solutions to a packing problem of this sort has a normal vector with two consecutive coefficients. Instantiating this result with the case where $\alpha = 1$, we obtain our main result.

Cutting planes

Before we proceed, we would like to stress some connections of this work to cutting plane theory. An inequality $cx \leq \lfloor \delta \rfloor$ is a *Gomory–Chvátal cutting plane* [16,7] of a polyhedron $P \subseteq \mathbb{R}^n$, if $c \in \mathbb{Z}^n$ is an integral vector and $cx \leq \delta$ is valid for P. The *Chvátal closure* P^c of P is the intersection of P with all

its Gomory–Chvátal cutting planes. If P is rational, then P^c is a rational polyhedron [32]. The separation problem for P^c is NP-hard [12]. A polytope P has *Chvátal-rank* one, if its Chvátal closure is the integer hull P_I of P, i.e., the convex hull of the integer vectors in P. Let QSTAB(G) be the *fractional stable set polytope* of a graph G, i.e., the polytope defined by non-negativity and clique inequalities, that is, respectively, $-x_v \leq 0$ for each vertex $v \in V$, and $\sum_{v \in K} x_v \leq 1$ for each (maximal) clique K in G. A famous example of a polytope of Chvátal-rank one is the fractional matching polytope and thus QSTAB(G), where G is a line graph. Giles and Trotter [15] showed that the Chvátal rank of QSTAB(G) is at least two, if G is claw-free. Chvátal, Cook and Hartman [8] showed that the Chvátal-rank of QSTAB(G) grows logarithmically in the number of nodes, even if the stability number of G is two and thus, even if G is claw-free. Oriolo [27] has shown that QSTAB(G) has Chvátal rank at least two, if G is a quasi-line graph.

An inequality $cx \leq \delta$ is called a *split cut* [9] of P if there exists an integer vector $\pi \in \mathbb{Z}^n$ and an integer π_0 such that $cx \leq \delta$ is valid for $P \cap \{x \in \mathbb{R}^n \mid \pi x \leq \pi_0\}$ and for $P \cap \{x \in \mathbb{R}^n \mid \pi x \geq \pi_0 + 1\}$. The *split closure* P^s of P is the intersection of P with all its split cuts and this is a rational polyhedron if P itself is rational [9,2]. The separation problem for the split closure is also NP-hard [4]. A polyhedron $P \subseteq \mathbb{R}^n$ has *split-rank* one, if $P^s = P_I$. Since a Gomory–Chvátal cutting plane is also a split cut one has $P^s \subseteq P^c$.

Both cutting plane calculi are simple procedures to derive valid inequalities for the integer hull of a polyhedron. We show below that a clique family inequality is a split cut for QSTAB(G) with $\pi(v) = 1$ if $v \in V_{p-1} \cup V_{\geq p}$, $\pi(v) = 0$ otherwise and $\pi_0 = \lfloor \frac{n}{p} \rfloor$. Thus, while the fractional stable set polytope of a quasi-line graph does not have Chvátal rank one, its split-rank is indeed one.

In the remainder of this section, we present the split-cut derivation of the clique-family inequality. Notice that the inequality

$$(4) \qquad (p-1) \sum_{v \in V_{p-1}} x(v) + p \sum_{v \in V_{\geq p}} x(v) \leq n = p \lfloor n/p \rfloor + r$$

is valid for QSTAB(G), since it is the result of summing up the clique inequalities corresponding to $\mathcal{F}$ and possibly applying the lower bounds $-x(v) \leq 0$ on vertices $v \in V_{\geq p}$ which are contained in more than p cliques. Now consider the disjunction

$$(5) \qquad \sum_{v \in V_{p-1} \cup V_{\geq p}} x(v) \leq \lfloor n/p \rfloor \qquad \vee \qquad \sum_{v \in V_{p-1} \cup V_{\geq p}} x(v) \geq \lfloor n/p \rfloor + 1\,.$$

Assume now the left inequality of the disjunction (5). Under this assumption we can write

$$(p - r - 1) \sum_{v \in V_{p-1}} x(v) + (p - r) \sum_{v \in V_{\geq p}} x(v) \leq (p - r) \sum_{v \in V_{p-1} \cup V_{\geq p}} x(v)$$
$$\leq (p - r) \lfloor n/p \rfloor,$$

where the first inequality follows from the lower bounds on the variables.

Assume now the right inequality of the disjunction (5). Together with (4) we can write

$$(p - r - 1) \sum_{v \in V_{p-1}} x(v) + (p - r) \sum_{v \in V_{\geq p}} x(v)$$
$$= (p - 1) \sum_{v \in V_{p-1}} x(v) + p \sum_{v \in V_{\geq p}} x(v) - r \sum_{v \in V_{p-1} \cup V_{\geq p}} x(v)$$
$$\leq (p - r) \lfloor n/p \rfloor.$$

2. From quasi-line graphs to circular interval graphs

In this section we first review some results concerning the structure of quasi-line graphs due to Chudnovsky and Seymour [6]. We then build upon these results to reduce the proof of the Ben Rebea conjecture to the case where the graph is a circular interval graph.

2.1. Circular Interval Graphs

A *circular interval graph* [6] $G = (V, E)$ is defined by the following construction, see Figure 1: Take a circle $\mathcal{C}$ and a set of vertices V on the circle. Take a subset of intervals $\mathcal{I}$ of $\mathcal{C}$ and say that $u, v \in V$ are adjacent if u and v are contained in one of the intervals.

Any interval used in the construction will correspond to a clique of G. Denote the family of cliques stemming from intervals by $\mathcal{K}_\mathcal{I}$ and the set of all cliques in G by $K(G)$. Without loss of generality, the (intervals) cliques of $\mathcal{K}_\mathcal{I}$ are such that none includes another. Moreover $\mathcal{K}_\mathcal{I} \subseteq K(G)$ and each edge of G is contained in a clique of $\mathcal{K}_\mathcal{I}$. Therefore, if we let $A \in \{0, 1\}^{m \times n}$ be the clique vertex incidence matrix of $\mathcal{K}_\mathcal{I}$ and V one can formulate the (weighted) stable set problem on a circular interval graph as a packing problem

$$\max \sum_{v \in V} c(v) x(v), \quad \text{where} \quad A x \leq \mathbf{1} \quad \text{and} \quad x(v) \in \{0, 1\}, \ \forall v \in V,$$
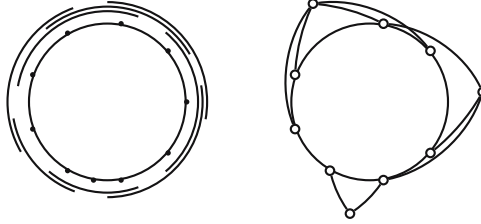
Figure 1. A circular interval graph

where the matrix A is a circular ones matrix (e.g. using clockwise ordering of the vertices).

We point out that the property above may be used as a characterization for circular interval graphs. In fact, it is easy to see that a graph $G(V, E)$ is a circular interval graph if and only if there exists an ordering of V and a set $\mathcal{K}_\mathcal{I}$ of cliques of G such that: (i) each edge of G is contained in a clique of $\mathcal{K}_\mathcal{I}$; (ii) the clique vertex incidence matrix of $\mathcal{K}_\mathcal{I}$ and V is a circular ones matrix. Finally, circular interval graphs are also called *proper circular arc graphs*, i.e., they are equivalent to the intersection graphs of arcs of a circle with no containment between arcs [6].

2.2. Fuzzy Circular Interval Graphs

Chudnovsky and Seymour [6] also introduced a *super-class* of circular interval graphs called *fuzzy circular interval graphs*. A graph $G(V, E)$ is a fuzzy circular interval if the following conditions hold.

(i) There is a map Φ from V to a circle $\mathcal{C}$.
(ii) There is a set of intervals $\mathcal{I}$ of $\mathcal{C}$, none including another, such that no point of $\mathcal{C}$ is an endpoint of more than one interval so that:
  (a) If two vertices u and v are adjacent, then $\Phi(u)$ and $\Phi(v)$ belong to a common interval.
  (b) If two vertices u and v belong to a same interval, which is not an interval with distinct endpoints $\Phi(u)$ and $\Phi(v)$, then they are adjacent.

In this case, we also say that the pair $(\Phi, \mathcal{I})$ gives a *fuzzy representation* of G.

In other words, in a fuzzy circular interval graph, adjacencies are completely described by the pair $(\Phi, \mathcal{I})$, except for vertices u and v such that $\mathcal{I}$ contains an interval with endpoints $\Phi(u)$ and $\Phi(v)$. For these vertices adjacency is fuzzy. If $[p, q]$ is an interval of $\mathcal{I}$ such that $\Phi^{-1}(p)$ and $\Phi^{-1}(q)$ are

both non-empty, then we call the cliques $(\Phi^{-1}(p), \Phi^{-1}(q))$ a *fuzzy pair*. Here $\Phi^{-1}(p)$ denotes the clique $\{v \in V \mid \Phi(v) = p\}$.

The left drawing of Figure 2 illustrates a section of a representation of a fuzzy circular interval graph G. The cliques $\Phi^{-1}(p)$ and $\Phi^{-1}(r)$ are fuzzy pairs, since p and r are the endpoints of an interval. The node sets $\Phi^{-1}(p) \cup \Phi^{-1}(q)$ and $\Phi^{-1}(q) \cup \Phi^{-1}(r)$ are cliques. The edges with one endpoint in $\Phi^{-1}(p)$ and the other in $\Phi^{-1}(r)$ are "fuzzy". The other interval which starts a little left from q and ends at s can be extended a little to the right of s, since $\Phi^{-1}(q) \cup \Phi^{-1}(r) \cup \Phi^{-1}(s)$ is a clique of G. Therefore the right drawing of Figure 2 shows another possible representation of the same graph.

Figure 2. Two different representations of a fuzzy circular interval graph

In the following, when referring to a fuzzy circular interval graph, we often consider a *fuzzy representation* $(\Phi, \mathcal{I})$ and detail the fuzzy adjacencies only when needed.

Let Q be a subset of V and v a vertex not in Q. We say that v is *complete* to Q if v is adjacent to each vertex of Q, while we say that v is *anticomplete* to Q if v is not adjacent to any vertex of Q.

Two disjoint cliques K_1 and K_2 of size at least two are a *homogeneous pair of cliques* [6] if each vertex $v \notin K_1 \cup K_2$ is: either complete to K_1 and K_2; or anticomplete to K_1 and K_2; or complete to K_1 (K_2) and anticomplete to K_2 (K_1). Trivially, if $[p, q]$ is an interval of $\mathcal{I}$ such that $\Phi^{-1}(p)$ and $\Phi^{-1}(q)$ are both of size at least two, then $\Phi^{-1}(p)$ and $\Phi^{-1}(q)$ is a homogeneous pair.

We also say that a homogeneous pair of cliques (K_1, K_2) is *proper* if every vertex of K_1 is neither complete nor anticomplete to K_2 and every vertex of K_2 is neither complete nor anticomplete to K_1. A graph is C_4-*free* if it does not have an induced subgraph isomorphic to a cordless cycle of length 4. For $X \subseteq V$, we denote by $G[X]$ the subgraph of G *induced by* X.

Lemma 1 ([5]). *Let (K_1, K_2) be a homogeneous pair of cliques. If (K_1, K_2) is proper, then the subgraph $G[K_1 \cup K_2]$ contains an induced C_4.*

Proof. For a vertex $u \in K_1$ let $d_2(u)$ be its degree with respect to K_2, that is $d_2(u) = |\{v \in K_2 : uv \in E\}|$. Let u_1 be a vertex of K_1 with maximum degree with respect to K_2. Since (K_1, K_2) is proper, u_1 has a non-neighbor z_2 in K_2.

The same applies to z_2 and K_1: z_2 has a neighbor $u_2 \in K_1$. Finally, there must exist a vertex $z_1 \in K_2$ that is a neighbor of u_1 and a non-neighbor of u_2 (otherwise $d_2(u_2) > d_2(u_1)$). It follows that $\{u_1, u_2, z_1, z_2\}$ induce a C_4. ∎

Lemma 2. *Let G be a fuzzy circular interval graph with a fuzzy representation $(\Phi, \mathcal{I})$. If no fuzzy pair contains an induced C_4, then G is a circular interval graph.*

Proof. Let $(\Phi^{-1}(p), \Phi^{-1}(q))$ be a fuzzy pair. This pair is homogenous but not proper by Lemma 1. Since it is not proper, there exists a vertex in $\Phi^{-1}(p)$ (resp. $\Phi^{-1}(q)$) that is either complete to anticomplete to $\Phi^{-1}(q)$ (resp. $\Phi^{-1}(p)$).

Suppose that $v \in \Phi^{-1}(p)$ is complete to $\Phi^{-1}(q)$. Then we can move $\Phi(v)$ by a small amount into the interior of the interval $[p, q]$. This yields a new representation $(\Phi', \mathcal{I})$ of the graph G that does not introduce new fuzzy pairs and reduces the number of vertices which are contained in a fuzzy pair by one.

Similarly, if $v \in \Phi^{-1}(p)$ is anticomplete from $\Phi^{-1}(q)$, we can move $\Phi(v)$ such that it is outside $[p, q]$. This operation yields a new mapping Φ'. In addition to that we must add an interval I covering v and its neighbors in $[p, q]$. Since v is adjacent to every vertex which is mapped to the half-open interval $[p, q)$ and since $v \cup \Phi'^{-1}([p, q))$ is a clique, this interval I can be chosen such that both of its endpoints are not contained in $\Phi'(V)$. This new representation $(\Phi', \mathcal{I} \cup \{I\})$ does also not introduce new fuzzy pairs – this is because each of the ends of the new interval is mapped to a single vertex of the graph – and reduces the number of vertices which are contained in a fuzzy pair by one.

We can iterate this process until there are no fuzzy pairs left. ∎

2.3. Decomposition of quasi-line graphs

Let G be a graph and $L(G)$ be its line graph. Notice that G can be build by considering a disjoint union of stars (associated to every vertex in G) and then identifying some of the edges. $L(G)$ can thus be built by considering a disjoint union of cliques and identifying some vertices. This construction has been generalized by Chudnovsky and Seymour [6] through the operations *glue* and *composition*.

A vertex v is *simplicial* if its neighbors form a clique. A *strip* (G, a, b) is a graph G together with two designated simplicial vertices a and b. Let (G, a, b) and (G', a', b') be two vertex-disjoint strips. The *glue* of (G, a, b) and (G', a', b') is the graph resulting from the union of $G \setminus \{a, b\}$ and $G' \setminus \{a', b'\}$

together with the adjunction of all possible edges between the neighbors of a (b) in G and the neighbors of a' (b') in G.

Let G_0 be a disjoint union of cliques with an even vertex set $V(G_0) = \{a_1, b_1, \ldots, a_n, b_n\}$. Let (G_i', a_i', b_i') be n strips that are vertex-disjoint, also from G_0. For $i = 1, \ldots, n$, let G_i be the graph obtained by gluing (G_{i-1}, a_i, b_i) with (G_i', a_i', b_i'). G_n is called the *composition* of the strips (G_i', a_i', b_i'), with the collection of disjoint cliques G_0.

We observed that a line graph can be built by considering a disjoint union of cliques and identifying some vertices. Gluing a strip that is an induced two-edge path, with a strip (S, a, b) results in the identification of a and b. Therefore any line graph G can be expressed as the composition of strips that are induced two-edge paths with G_0 made of $|V(G)|$ cliques. If we now replace induced two-edge paths strips by fuzzy linear interval strips (a superclass), we get a large class of quasi-line graphs. Chudnovsky and Seymour proved in fact the following structural result.

Theorem 3 (Chudnovsky and Seymour [6]). *A connected quasi-line graph G is either a fuzzy circular interval graph, or it is the composition of fuzzy linear interval strips with a collection of disjoint cliques.*

Chudnovsky and Seymour were also able to give a complete characterization of the stable set polytope of quasi-line graphs that are *not* fuzzy circular interval graphs. Let $\mathcal{F} = \{K_1, K_2, \ldots, K_{2n+1}\}$ be an odd set of cliques of G. Let $T \subseteq V$ be the set of vertices which are covered by at least two cliques of $\mathcal{F}$. Then the inequality $\sum_{v \in T} x(v) \leq n$ is a valid inequality for STAB(G) and inequalities of this type are called Edmonds inequalities.

Theorem 4 (Chudnovsky and Seymour [6]). *If G is the composition of fuzzy linear interval strips with a collection of disjoint cliques, then all non trivial facets of STAB(G) are Edmonds inequalities.*

2.4. The reduction to circular interval graphs

Observe that Edmonds inequalities are special clique family inequalities associated with $\mathcal{F}$ and $p = 2$. Therefore, we may give a positive answer to the Ben Rebea Conjecture if we prove that it holds for fuzzy circular interval graphs. We now show that it will be enough to prove the conjecture for circular interval graphs.

Lemma 5. *Let F be a facet of STAB(G), where G is a fuzzy circular interval graph. Then F is also a facet of STAB(G'), where G' is a circular interval graph and is obtained from G by removing some edges.*

Proof. Suppose that F is induced by the valid inequality $ax \leq \beta$, where a is a vector indexed by $V(G)$. An edge e is F-*critical*, if $ax \leq \beta$ is not valid for $\text{STAB}(G \backslash e)$. If e is not F-critical, then F is also a facet of $\text{STAB}(G \backslash e)$.

Let (Φ, I) be a fuzzy representation of G. For every fuzzy pair (K_1, K_2), we remove all the edges connecting a vertex in K_1 to a vertex in K_2 that are non-F-critical. We end up with a fuzzy circular interval graph G' which has the same fuzzy representation (Φ, I) as G.

We claim that no fuzzy pair of G' contains a C_4 and thus by Lemma 2, G' is a circular interval graph. Moreover since we remove only non F-critical edges, F is still a facet of $\text{STAB}(G')$.

Suppose the contrary that there exists a fuzzy pair (K_1, K_2) of G' that contains a C_4. Say $V(C_4) = \{u_1, u_2, v_1, v_2\}$ with $u_1, u_2 \in K_1$, $v_1, v_2 \in K_2$, $u_1v_1, u_2v_2 \in E(C_4)$. The edge u_1v_1 is F-critical. Hence there exists a set S containing u_1 and v_1 such that S violates $ax \leq \beta$ and S is stable in $G' \backslash u_1 v_1$. Since K_1 and K_2 form an homogeneous pair, u_1 and u_2 are adjacent to the same vertices in $G' \backslash K_2$. This implies that $(S \backslash u_1) \cup \{u_2\}$ is a stable set and therefore satisfies the inequality. Therefore $a(u_2) < a(u_1)$ (else (u_1, v_1) is not F-critical). Applying the same argument to u_2v_2 leads to $a(u_1) < a(u_2)$. Which is a contradiction. ∎

Remark. We would like to point out here that the following statement can be proved in a similar way as the proof of Lemma 5: Let F be a facet of $\text{STAB}(G)$ where G is a general graph. There exists G', obtained from G by removing some edges, such that F is also a facet of $\text{STAB}(G')$ and G' does not contain any pair of cliques which is proper and homogeneous.

Lemma 5 shows that each facet of a fuzzy circular interval graph is a facet of a circular interval graph which is obtained via the deletion of some edges. A clique family inequality of the thereby obtained circular interval graph is a clique family inequality of the original fuzzy circular interval graph. Therefore, we now only have to establish the Ben Rebea conjecture for the class of circular interval graphs. Recall that the stable set polytope of a circular interval graph is the integer hull of a polyhedron of the form $\{x \in \mathbb{R}^n \, | \, Ax \leq 1, \, x \geq 0\}$, where $A \in \{0,1\}^{m \times n}$ is a circular ones matrix.

3. Slicing and separation

In this section we show that the separation problem for $\text{STAB}(G)$ reduces to a min-cost circulation problem if G is a circular interval graph. For this, we present a membership algorithm of Gijswijt [14] and develop it further to retrieve a separating hyperplane.

Let P be a polytope $P = \{x \in \mathbb{R}^n \mid Ax \leq b, x \geq 0\}$, where $A \in \{0,1\}^{m \times n}$ is a circular ones matrix and $b \in \mathbb{Z}^m$ an integral vector. We consider the separation problem for the integer hull P_I of P:

Given $x^* \in \mathbb{R}^n$, determine, whether $x^* \in P_I$ and, if not, determine an inequality $cx \leq \delta$ which is valid for P_I and satisfies $cx^* > \delta$.

Following Bartholdi, Orlin and Ratliff [3], we consider the unimodular transformation $x = Ty$, where T is the unimodular matrix

$$
(6) \qquad T = \begin{pmatrix} \frac{1}{-1} & 1 & & & \\ & -1 & 1 & & \\ & & -1 & & \\ & & & \ddots & \\ & & & & \frac{1}{-1} \ 1 \end{pmatrix}.
$$

The problem then reads, separate $y^* = T^{-1}x^*$ from the integer hull Q_I of the polytope Q defined by the system

$$
(7) \qquad \begin{pmatrix} A \\ -I \end{pmatrix} Ty \leq \begin{pmatrix} b \\ 0 \end{pmatrix}.
$$

In the following we denote the inequality system (7) by $By \leq d$. Let us rewrite the matrix B as $B = (N|v)$, i.e., v is the n-th column of B. Observe that, by construction, v is also the last column of $\begin{pmatrix} A \\ -I \end{pmatrix}$.

Each row of the matrix N has at most one entry which is $+1$ and at most one entry which is -1. All other entries are 0. The matrix N is thus totally unimodular. Thus, whenever $y(n)$ is set to an integer $\beta \in \mathbb{Z}$, the possible values for the variables $y(1), \ldots, y(n-1)$ define an integral polytope $Q_\beta = Q \cap \{y \in \mathbb{R}^n \mid y(n) = \beta\}$. We call this polytope Q_β the *slice* of Q defined by β.

Since T is unimodular, the corresponding slice of the original polyhedron $P \cap \{x \in \mathbb{R}^n \mid \sum_{i=1}^n x(i) = \beta\}$ is an integral polyhedron. From this it is already easy to see that the split-rank of P is one. However, we present a combinatorial separation procedure for the integer hull P_I of P which computes a split cut via the computation of a negative cycle.

If $y^*(n)$ is integral, then y^* lies in Q_I if and only if $y^* \in Q_{y^*(n)}$. Therefore we assume in the following that $y^*(n)$ is not integral and let β be an integer such that $\beta < y^*(n) < \beta + 1$ and let $1 > \mu > 0$ be the real number with $y^*(n) = \beta + 1 - \mu$. Furthermore, let Q_L and Q_R be the left slice Q_β and right slice $Q_{\beta+1}$ respectively. A proof of the next lemma follows from basic convexity.

Lemma 6. *The point y^* lies in Q_I if and only if there exist $y_L \in Q_L$ and $y_R \in Q_R$ such that*

$$y^* = \mu\, y_L + (1 - \mu)y_R\,.$$

In the following we denote by $\overline{y} \in \mathbb{R}^{n-1}$ the vector of the first $n-1$ components of $y \in \mathbb{R}^n$. From the above discussion one has $y^* \in Q_I$ if and only if the following linear constraints have a feasible solution.

$$\begin{aligned} \overline{y_L} + \overline{y_R} &= \overline{y^*} \\ N\overline{y_L} &\le \mu\, d_L \\ N\overline{y_R} &\le (1 - \mu)\, d_R\,, \end{aligned}$$

(8)

where $d_L = d - \beta v$ and $d_R = d - (\beta + 1)v$.

Using Farkas' Lemma [33], it follows that the system (8) is feasible, if and only if $\sum_{i=1}^{n-1} \lambda(i)y^*(i) + \mu f_L d_L + (1 - \mu)f_R d_R$ is nonnegative, whenever λ, f_L and f_R satisfy

$$\begin{aligned} \lambda + f_L N &= 0 \\ \lambda + f_R N &= 0 \\ f_L, f_R &\ge 0. \end{aligned}$$

(9)

Now $\lambda + f_L N = 0$ and $\lambda + f_R N = 0$ is equivalent to $\lambda = -f_L N$ and $f_L N = f_R N$. Thus (8) defines a feasible system, if and only if the optimum value of the following linear program is nonnegative:

$$\begin{aligned} \min -f_L N\, \overline{y^*} &+ \mu f_L d_L + (1 - \mu)f_R d_R \\ f_L N = f_R N, \quad f_L, f_R &\ge 0. \end{aligned}$$

(10)

Let w be the negative sum of the columns of N. Then (10) is the problem of finding a minimum cost circulation, see, e.g. [34] in the directed graph $D = (U, \mathcal{A})$ defined by the edge-node incidence matrix

$$M = \begin{pmatrix} N & w \\ -N & -w \end{pmatrix}$$

(11)

with edge weights $\mu(-N\, \overline{y^*} + d_L),\ (1 - \mu)(-N\, \overline{y^*} + d_R)$.

Thus $y^* \notin Q_I$ if and only if there exists a negative cycle in $D = (U, \mathcal{A})$. The membership problem for Q_I thus reduces to the problem of detecting a negative cycle in D, see [14].

A separating split cut for y^* is an inequality which is valid for Q_L and Q_R but not valid for y^*. The inequality $f_L N\overline{y} \le f_L d_L$ is valid for Q_L and

the inequality $f_R N \overline{y} \leq f_R d_R$ is valid for Q_R. The corresponding disjunctive inequality (see, e.g., [26]) is the inequality

$$(12) \qquad \begin{aligned} & f_L N \overline{y} + c(n) y(n) \leq \delta, \\ & \text{where} \ \ c(n) = f_L d_L - f_R d_R \ \ \text{and} \ \ \delta = (\beta + 1) f_L d_L - \beta f_R d_R. \end{aligned}$$

The polytopes Q_L and Q_R are defined by the systems

$$(13) \qquad \begin{aligned} y(n) &= \beta \\ N \overline{y} + v\, y(n) &\leq d \end{aligned} \qquad \text{and} \qquad \begin{aligned} y(n) &= \beta + 1 \\ N \overline{y} + v\, y(n) &\leq d \end{aligned}$$

respectively.

Let $f_{L,0}$ be the number $c(n) - f_L v$. Then the inequality (12) can be derived from the system defining Q_L with the weights $(f_{L,0}, f_L)$, i.e., the inequality can be obtained as $f_{L,0} \cdot y(n) + f_L \cdot (N \overline{y} + v y(n)) \leq f_{L,0} \cdot \beta + f_L d$. Notice that, if y^* can be separated from Q_I, then $f_{L,0}$ must be positive. This is because y^* violates (12) and satisfies the constraints (13) on the left, where the equality $y(n) = \beta$ in the first line is replaced with $y(n) \geq \beta$. Let $f_{R,0}$ be the number $c(n) - f_R v$. Then the inequality (12) can be derived from the system defining Q_R with the weights $(f_{R,0}, f_R)$. Notice that, if y^* can be separated from Q_I, then $f_{R,0}$ must be negative.

A negative cycle in a graph with m edges and n nodes can be found in time $O(mn)$, see, e.g. [1]. Translated back to the original space and to the polyhedron P this gives the following theorem.

Theorem 7. *The separation problem for P_I can be solved in time $O(mn)$. Moreover, if $x^* \in P$ and $x^* \notin P_I$ one can compute in $O(mn)$ a split cut $cx \leq \delta$ which is valid for P_I and separates x^* from P_I together with a negative integer $f_{R,0}$, a positive integer $f_{L,0}$ and a vector f_L, f_R, which is the incidence vector of a simple negative cycle of the directed graph $D = (U, \mathcal{A})$ with edge-node incidence matrix and weights as in (11), such that $cx \leq \delta$ is derived from the systems*

$$(14) \qquad \begin{aligned} \mathbf{1}x &\leq \beta \\ Ax &\leq b \\ -x &\leq 0 \end{aligned} \qquad \text{and} \qquad \begin{aligned} -\mathbf{1}x &\leq -(\beta + 1) \\ Ax &\leq b \\ -x &\leq 0, \end{aligned}$$

with the weights $f_{L,0}, f_L$ and $|f_{R,0}|, f_R$ respectively.

The above theorem gives an explicit derivation of the separating hyperplane as a split cut of P. We have the following corollary.

Corollary 8. *The integer hull P_I is the split closure of P.*

4. The facets of P_I for the case $b = \alpha \cdot 1$

In this section we study the facets of P_I, where $P = \{x \in \mathbb{R}^n \mid Ax \leq b, x \geq 0\}$, where A is a circular ones matrix and b is an integer vector of the form $\alpha \mathbf{1}, \alpha \in \mathbb{N}$. For this, we actually inspect how the facets of the transformed polytope Q described in Section 3 are derived from the systems (13) and apply this derivation to the original system. It will turn out that the facet normal-vectors of P_I have only two integer coefficients, which are in addition consecutive. Since the stable set polytope of a circular interval graph is defined by such a system with $\alpha = 1$, we can later instantiate the results of this section to this special case. We can assume that the rows of A are inclusion-wise maximal, that is, for each row i, there does not exists another row $j \neq i$ such that $a_{jh} \geq a_{ih}$, for each $h = 1, \ldots, n$.

Let F be a facet of Q_I and let y^* be in the relative interior of F. This facet F is generated by the unique inequality (12), which corresponds to a simple cycle of (10) of weight 0. Furthermore assume that F is not induced by an inequality $y(n) \leq \gamma$ with $\gamma \in \mathbb{Z}$. Since F is a facet of the convex hull of integer points of two consecutive slices, we can assume that $y^*(n) = \beta + 1/2$ and thus that $\mu = 1/2$ in (10). This allows us to rewrite the objective function of problem (10) as follows:

$$(15) \qquad \min\left(s^* + \frac{1}{2}v\right)f_L + \left(s^* - \frac{1}{2}\right)f_R,$$

where s^* is the slack vector

$$(16) \qquad s^* = \begin{pmatrix} \alpha \mathbf{1} \\ \mathbf{0} \end{pmatrix} - By^* = \begin{pmatrix} \alpha \mathbf{1} \\ \mathbf{0} \end{pmatrix} - \begin{pmatrix} A \\ -I \end{pmatrix} x^* \geq \mathbf{0}.$$

The point x^* in (16) is $x^* = Ty^*$. Notice that x^* satisfies the system $Ax \leq \alpha \mathbf{1}$.

Furthermore, we are interested in the facets of Q_I which are not represented by the system $By \leq d$. If F is such a facet, then one can translate y^* away from Q_I, without changing $y^*(n) = \beta + 1/2$, such that $y^* \notin Q_I$ and $By^* \leq d$ with the property that the facet we are considering is the unique inequality (12), where f_L, f_R is a simple negative cycle in the graph $D = (U, \mathcal{A})$.

In the following we denote $U = \{1, \ldots, n\}$, where node i corresponds to the i-th column of the matrix M in (11). Notice that $\mathcal{A}$ partitions in two classes of arcs $\mathcal{A}_L$ and $\mathcal{A}_R$. The arcs $\mathcal{A}_R$ are simply the reverse of the arcs $\mathcal{A}_L$. $\mathcal{A}_L$ consists of two sets of arcs $\mathcal{S}_L$ and $\mathcal{T}_L$, where $\mathcal{S}_L$ is the set of arcs associated with inequalities $Ax \leq \alpha \mathbf{1}$ and $\mathcal{T}_L$ are the arcs stemming from the lower bounds $x \geq 0$. Likewise $\mathcal{A}_R$ can be partitioned into $\mathcal{S}_R$ and $\mathcal{T}_R$. In other
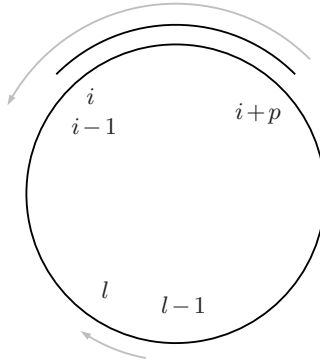
Figure 3. The incidence vector of a row of A consists of the nodes $\{i, i+1, \ldots, i+p\}$ which are consecutive on the cycle in clockwise order. Its corresponding arc in $\mathcal{S}_L$ is the arc $(i+p, i-1)$. The arc $(l-1, l)$ in $\mathcal{T}_L$ corresponds to the lower bound $x(l) \geq 0$.

words, if we look at the arc-node incidence matrix M in (11), the rows of M appear in the order $\mathcal{S}_L, \mathcal{T}_L, \mathcal{S}_R, \mathcal{T}_R$.

In particular, let a denote a row vector of A. Since A is a circular ones matrix one has $ax \leq \alpha \equiv \sum_{h=0}^{p} x(i+h) \leq \alpha$ for some suitable i and p, where computation is modulo n, so $x_n \equiv x_0$, $x_{n+1} \equiv x_1$, etc. It is straightforward to see that $ax \leq \alpha$ generates the arcs $(i+p, i-1) \in \mathcal{S}_L$ and $(i-1, i+p) \in \mathcal{S}_R$ of $\mathcal{A}$, see Figure 3. The weights of the two arcs coincide, if $n \notin \{i, i+1, \ldots, i+p\}$ and is exactly the slack $\alpha - \sum_{h=0}^{p} x^*(i+h)$ in this case. Otherwise, the weight of the arc $(i+p, i-1)$ is $\alpha - \sum_{h=0}^{p} x^*(i+h) + 1/2$ and the weight of the arc $(i-1, i+p)$ is $\alpha - \sum_{h=0}^{p} x^*(i+h) - 1/2$.

On the other hand, a lower bound $-x_i \leq 0$ generates the two arcs $(i-1, i) \in \mathcal{T}_L$ and $(i, i-1) \in \mathcal{T}_R$. The weight of both arcs is equal to $x^*(i)$, if $i \neq n$. If $i = n$, the arc $(n-1, n) \in \mathcal{T}_L$ has weight $x^*(n) - 1/2$ and $(n, n-1) \in \mathcal{T}_R$ has weight $x^*(n) + 1/2$.

Since the slacks are non-negative, the arcs whose cost is equal to the corresponding slack minus $\frac{1}{2}$ are the only candidates to have a negative cost. We call those *light* arcs. Consequently we call those arcs whose cost is equal to the slack plus $\frac{1}{2}$ *heavy*. Observe that the light arcs belong to $\mathcal{S}_R \cup \{(n-1, n)\}$.

Lemma 9. *Let $\mathcal{C}$ be a simple negative cycle in D, then the following holds:*

(a) *$\mathcal{C}$ contains strictly more light arcs than heavy ones.*
(b) *An arc of $\mathcal{C}$ in $\mathcal{S}_L$ ($\mathcal{T}_L$) cannot be immediately followed or preceded by an arc in $\mathcal{S}_R$ ($\mathcal{T}_R$).*
(c) *The cycle $\mathcal{C}$ contains at least one arc of $\mathcal{S}_R$ or contains no arc of $\mathcal{S}_L \cup \mathcal{S}_R$.*

Proof. (a) follows from the fact that the slacks are nonnegative. (b) follows from our assumption that the rows of the matrix A are maximal and that $\mathcal{C}$ is simple.

To prove (c) suppose that the contrary holds. It follows that $(n-1,n)$ is in $\mathcal{C}$, because it is the only light arc not in $\mathcal{S}_R$. We must reach $n-1$ on the cycle without using heavy arcs.

Each arc in $\mathcal{S}_L$ with starting node n is heavy. Thus $(n-1,n)$ is followed by $(n,1) \in \mathcal{T}_L$. Suppose that $(n-1,n)$ is followed by a sequence of arcs in $\mathcal{T}_L$ leading to i and let $(i,j) \notin \mathcal{T}_L$ be the arc which follows this sequence. It follows from (b) that $(i,j) \notin \mathcal{T}_R$ and thus that $(i,j) \in \mathcal{S}_L$. Since (i,j) cannot be heavy, we have $1 \leq j < i < n$. This is a contradiction to the fact that $\mathcal{C}$ is simple, since we have a sub-cycle contained in $\mathcal{C}$, defined by (i,j) and $(j,j+1),\ldots,(i-1,i)$. ∎

Lemma 10. *If there exists a simple cycle $\mathcal{C}$ of D with negative cost, then there exists a simple cycle $\mathcal{C}'$ of D with negative cost that does not contain any arc from $\mathcal{S}_L$.*

Proof. Suppose that $\mathcal{C}$ contains an arc from the set $\mathcal{S}_L$. We know from Lemma 9 that the cycle $\mathcal{C}$ contains at least one arc of $\mathcal{S}_R$. Lemma 9 implies that $\mathcal{C}$ has an arc in $\mathcal{S}_L$, followed by arcs in $\mathcal{T}_L$ or $\mathcal{T}_R$ but not both, followed by an arc in $\mathcal{S}_R$. We first consider the case that the intermediate arcs are all in $\mathcal{T}_L$.
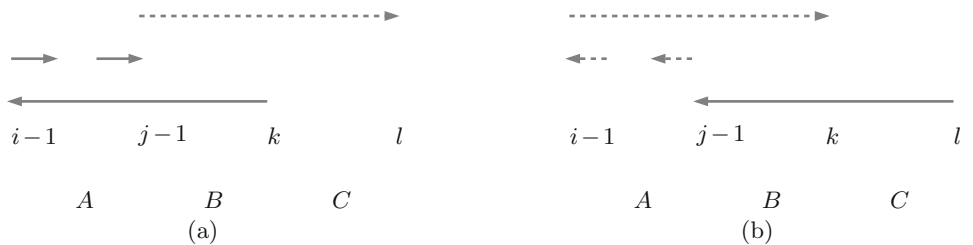

Figure 4. (a) depicts an arc $(k,i-1) \in \mathcal{S}_L$, followed by arcs in $\mathcal{T}_L$ and the arc $(j-1,l) \in \mathcal{S}_R$. (b) depicts the situation where the intermediate arcs are in $\mathcal{T}_R$.

This situation is depicted in Figure 4, (a). The arc in $\mathcal{S}_L$ is $(k,i-1)$. This is followed by the arcs $(i-1,i),\ldots,(j-2,j-1)$ in $\mathcal{T}_L$ and the arc $(j-1,l)$ in $\mathcal{S}_R$. Let this be the path $\mathcal{P}_1$. We now show that we can replace this path with the path $\mathcal{P}_2 = (k,k+1),\ldots,(l-1,l)$ consisting of arcs in $\mathcal{T}_L$. We proceed as follows. First we show that the weight of this path is at most the weight of the original path, where we ignore the addition of $\pm 1/2$ to the arc-weights. Let

light($\mathcal{P}$) and heavy($\mathcal{P}$) be the number of light and heavy edges in a path $\mathcal{P}$, respectively. We then show that light($\mathcal{P}_2$)$-$heavy($\mathcal{P}_2$)$=$light($\mathcal{P}_1$)$-$heavy($\mathcal{P}_1$), from which we can conclude the claim in this case.

Consider the set of indices $\mathcal{A} = \{i,\ldots,j-1\}$, $\mathcal{B} = \{j,\ldots,k\}$ and $\mathcal{C} = \{k+1,\ldots,l\}$ and the numbers $A = \sum_{\mu\in\mathcal{A}}x^*(\mu)$, $B = \sum_{\mu\in\mathcal{B}}x^*(\mu)$ and $C = \sum_{\mu\in\mathcal{C}}x^*(\mu)$. Ignoring the eventual addition of $\pm 1/2$ to the edge weights, we have that the weight of $\mathcal{P}_2$ is C and that of $\mathcal{P}_1$ is $\alpha-(A+B)+A+\alpha-(B+C)$ and suppose that this is less than C. Then $B+C>\alpha$ which is not possible, since x^* satisfies the constraints $Ax\leq\alpha\mathbf{1}$. Thus, if none of the edges in $\mathcal{P}_1$ and $\mathcal{P}_2$ is heavy or light, the weight of $\mathcal{P}_2$ is at most the weight of $\mathcal{P}_1$.

Suppose now that $n\in\mathcal{A}$. Then $\mathcal{P}_1$ contains exactly one heavy edge $(k,i-1)$ and one light edge $(n-1,n)$. The path $\mathcal{P}_2$ contains no heavy or light edge. Suppose that $n\in\mathcal{B}$, then $\mathcal{P}_1$ contains exactly one heavy edge $(k,i-1)$ and one light edge $(j-1,l)$. $\mathcal{P}_2$ does not contain a heavy or light edge. If $n\in\mathcal{C}$, then $\mathcal{P}_1$ contains exactly one light edge $(j-1,l)$ and no heavy edge. $\mathcal{P}_2$ also contains exactly one light edge $(n-1,n)$. This concludes the claim for the case that an arc of $\mathcal{S}_L$ is followed by arcs of $\mathcal{T}_L$ and an arc of $\mathcal{S}_R$.

The case where the intermediate arcs belong to $\mathcal{T}_R$ is depicted in Figure 4, (b). The assertion follows by a similar argument. ∎

Combining Theorem 7 with the above lemma we obtain the following theorem.

Theorem 11. *Let $P = \{x\in\mathbb{R}^n \mid Ax\leq\alpha\mathbf{1},x\geq 0\}$ be a polyhedron, where $A\in\{0,1\}^{m\times n}$ is a circular ones matrix and $\alpha\in\mathbb{N}$ a positive integer. A facet of P_I is of the form*

$$a\sum_{v\in T}x(v) + (a-1)\sum_{v\notin T}x(v) \leq a\,\beta, \tag{17}$$

where $T\subseteq\{1,\ldots,n\}$ and $a,\beta\in\mathbb{N}$.

Proof. Theorem 7 implies that a facet which is not induced by $Ax\leq\alpha\mathbf{1}$, $x\geq 0$ or $\mathbf{1}x\leq\gamma$ is a nonnegative integer combination of the system on the left in (14) with nonnegative weights $f_{L,0},f_L$. Lemma 10 implies that f_L can be chosen such that the only nonzero $(+1)$ entries of f_L are corresponding to lower bounds $-x(v)\leq 0$. The theorem thus follows with $a = f_{0,L}$ and T set to those variables, whose lower bound inequality does not appear in the derivation. ∎

5. The solution of the Ben Rebea Conjecture

Let G be a circular interval graph and let $\mathcal{K}_\mathcal{I}$ be the family of cliques stemming from the intervals in the definition of G (see Section 2). Then $P = \{x \in R^n \mid Ax \leq \mathbf{1}, x \geq 0\}$ where the 0/1 matrix A, corresponding to the cliques $\mathcal{K}_\mathcal{I}$, has the circular ones property. Theorem 11 implies that any facet of STAB(G) is of the form

$$\text{(18)} \qquad a \sum_{v \in T} x(v) + (a - 1) \sum_{v \notin T} x(v) \leq a \cdot \beta,$$

where $T \subseteq \{1, \ldots, n\}$ and $a, \beta \in \mathbb{N}$.

We now show that a facet F, which is not induced by an inequality of $Ax \leq \mathbf{1}, x \geq 0$ is induced by a clique family inequality associated with some set of cliques $\mathcal{F} \subseteq \mathcal{K}_I$ and some integer p. Recall from Theorem 7 that any facet of this kind can be derived from the system

$$\text{(19)} \qquad \begin{aligned} -\mathbf{1}x &\leq -(\beta + 1) \\ Ax &\leq \mathbf{1} \\ -x &\leq 0, \end{aligned}$$

with weights $|f_{R,0}|, f_R$, where $f_{R,0}$ is a negative integer while f_R is a 0-1 vector. A *root* of F is a stable set, whose characteristic vector belongs to F. In particular, we have that the multiplier $f_R(v)$ associated with a lower bound $-x(v) \leq 0$ must be 0 if v belongs to a root of size $\beta + 1$. If v does not belong to a root of size β or to a root of size $\beta + 1$, then the facet is induced by $x(v) \geq 0$. Thus if $v \notin T$, then v belongs to a root of size $\beta + 1$.

Let $\mathcal{F} = \{K \in \mathcal{K}_I \mid f_R(K) \neq 0\}$ and $p = a + |f_{R,0}|$. The multiplier $|f_{R,0}|$ must satisfy

$$\begin{aligned} -|f_{R,0}| + |\{K \in \mathcal{F} \mid v \in K\}| &= a - 1, \quad \forall v \notin T; \\ -|f_{R,0}| + |\{K \in \mathcal{F} \mid v \in K\}| &= a, \quad \forall v \in T, \ v \text{ is in a root of size } \beta + 1; \\ -|f_{R,0}| + |\{K \in \mathcal{F} \mid v \in K\}| &\geq a, \quad \forall v \in T, \ v \text{ is not in a root of size } \beta + 1; \\ -|f_{R,0}|(\beta + 1) + |\mathcal{F}| &= a\beta. \end{aligned}$$

Observe that $|\mathcal{F}| = (a + |f_{R,0}|)\beta + |f_{R,0}|$ and therefore $r = |\mathcal{F}| \mod p = |f_{R,0}|$. Moreover, any vertex not in T belongs to exactly $p - 1$ cliques from $\mathcal{F}$, while each vertex in T belongs to at least p cliques from $\mathcal{F}$. Therefore, inequality (18) is the clique family inequality associated with $\mathcal{F}$ and p. In particular since $a \geq 1$ and $|f_{R,0}| \geq 1$, it follows that $p \geq 2$. We may therefore state the following theorem.

Theorem 12. *Let G be a circular interval graph. Then any facet of* STAB(G), *which is not induced by an inequality of the system $Ax \leq \mathbf{1}$, $x \geq 0$, is a clique family inequality associated with some $\mathcal{F}$ and p such that $|\mathcal{F}| \mod p \neq 0$.*

If we combine this result with Lemma 5, Theorem 4 and we recall that Edmonds inequalities are also clique family inequalities associated with $|\mathcal{F}|$ odd and $p=2$, we obtain the following.

Theorem 13. *Let G be a quasi-line graph. Any non-trivial facet of* STAB(G) *is a clique family inequality associated with some $\mathcal{F}$ and p such that $|\mathcal{F}| \mod p \neq 0$.*

The Ben Rebea conjecture is now almost settled. Inspecting it again, we observe that apart from the statement that the stable set polytope is described by nonnegativity, clique and clique family inequalities it contains also conditions on $\mathcal{F}$ and p. We may assume that the cliques in the family $\mathcal{F}$ are maximal [27]. What remains is the condition $|\mathcal{F}| > 2p \geq 4$. This is settled in the following, where we also show that clique family inequalities are facet inducing only if $V_{\geq p} \neq \emptyset$.

Lemma 14. *A clique family inequality associated with $\mathcal{F}$ and p is facet inducing only if $V_{\geq p} \neq \emptyset$.*

Proof. If $V_{\geq p} = \emptyset$, then the clique family inequality associated with $\mathcal{F}$ and p reads:

$$(20) \qquad (p-r-1) \sum_{v \in V_{p-1}} x(v) \leq (p-r) \left\lfloor \frac{n}{p} \right\rfloor.$$

NB: $r \neq 0$ since otherwise, the inequality reads $(p-1)\sum_{v \in V_{p-1}} x(v) \leq n$ and is dominated by the sum of the clique inequalities in $\mathcal{F}$, a contradiction.

The vertices of $V_{\geq p-1}$ are covered by $p-1$ cliques of $\mathcal{F}$. Thus the inequality $\sum_{V_{p-1}} x(v) \leq \left\lfloor \frac{n}{p-1} \right\rfloor$ is valid for STAB(G). We will prove that this inequality dominates (20). It is trivial if $p-r-1=0$. Otherwise, we simply have to prove that $\left\lfloor \frac{n}{p-1} \right\rfloor < \frac{p-r}{p-r-1} \left\lfloor \frac{n}{p} \right\rfloor$. This is true if and only if $(p-r-1)\left\lfloor \frac{n}{p-1} \right\rfloor < (p-r)\left\lfloor \frac{n}{p} \right\rfloor$ i.e., if and only if $n - r' - r\left\lfloor \frac{n}{p-1} \right\rfloor < n-r-r\left\lfloor \frac{n}{p} \right\rfloor$ where $r' = n \mod (p-1)$. Now clearly $\left\lfloor \frac{n}{p-1} \right\rfloor \geq \left\lfloor \frac{n}{p} \right\rfloor$. If $\left\lfloor \frac{n}{p-1} \right\rfloor = \left\lfloor \frac{n}{p} \right\rfloor$, it is clear that $r' > r$ since $\left\lfloor \frac{n}{p} \right\rfloor \neq 0$ and the result follows. If $\left\lfloor \frac{n}{p-1} \right\rfloor \geq \left\lfloor \frac{n}{p} \right\rfloor + 1$, the result holds if $r' > 0$ or $r' = 0$ and $\left\lfloor \frac{n}{p-1} \right\rfloor > \left\lfloor \frac{n}{p} \right\rfloor + 1$. If $r' = 0$ and $\left\lfloor \frac{n}{p-1} \right\rfloor = \left\lfloor \frac{n}{p} \right\rfloor + 1$,

inequality (20) and $\sum_{V_{p-1}} x(v) \leq \lfloor \frac{n}{p-1} \rfloor$ coincide but since $r' = 0$, the later inequality is again dominated by the sum of the clique inequalities in $\mathcal{F}$, a contradiction. ∎

Lemma 15. *Let G be a quasi-line graph and $(\mathcal{F}, p)$ a pair such that*

$$(21) \qquad (p - r - 1) \sum_{v \in V_{p-1}} x(v) + (p - r) \sum_{v \in V_{\geq p}} x(v) \leq (p - r) \left\lfloor \frac{|\mathcal{F}|}{p} \right\rfloor$$

is a facet of $\mathrm{STAB}(G)$. If $|\mathcal{F}| < 2p$, then the inequality (21) is a clique inequality.

Proof. We know from the previous lemma that $V_{\geq p} \neq \emptyset$. Since $\lfloor \frac{|\mathcal{F}|}{p} \rfloor = 1$, if $V_{p-1} = \emptyset$ or $p - r = 1$, then the inequality (21) is a clique inequality, and we are done. Therefore we may assume that $V_{p-1} \neq \emptyset$ and $p - r > 1$. Since the inequality is facet inducing, then $p - r = 2$ and it reads:

$$(22) \qquad \sum_{v \in V_{p-1}} x(v) + 2 \sum_{v \in V_{\geq p}} x(v) \leq 2 .$$

Trivially, the inequality is also facet-inducing for the induced subgraph $G' = G[V_{p-1} \cup V_{\geq p}]$. A full description of the stable set polytope of graphs with stability number less than three, as G', is given in [21]. There it is shown that an inequality $\sum_{v \in A} x(v) + 2 \sum_{v \in B} x(v) \leq 2$, with A and B both non-empty, is facet inducing only if B is a clique, A and B are complete and there is an odd antihole in $G[A]$. But no vertex of a quasi-line graph is complete to an odd antihole (from the definition of quasi-line graphs), so there is a contradiction. ∎

We may therefore state our main result:

Theorem 16. *Ben Rebea's conjecture is true.*

Acknowledgements

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